



User Instruction & Installation Manual

FH380 Remote Control Variable Speed Twin Head Metal Halide Searchlight



Product Reference Number:

A7210 - FH380RC 1200w Twin Head 240v

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1 - Introduction

It is imperative that this manual is read carefully and understood before installing your equipment. For your future reference please keep this manual in a safe place.

Thank you for specifying a product from the Francis Searchlights range. All Francis products are designed to give complete customer satisfaction and are manufactured to the highest engineering standards to ensure optimum performance and service life.

The Francis FH range combines features proven over many years service in the most hazardous conditions in both marine and land installations.

To prolong the life and performance of your product, we recommend that you only specify Francis Searchlights spare parts. This will also ensure that any warranties on your equipment will not be invalidated. Information on spares ordering and parts is provided in this manual.

Should you ever need to contact Francis Searchlights Ltd. regarding your equipment, please always quote the Product Serial Number.

2 - Safety Precautions

The following instructions must be adhered to, to ensure a safe working environment and the safety of the user.

Note: When unpacking or manoeuvring the searchlight into its fixing position, suitable lifting points must be used to prevent damage to the equipment or personal injury.

- Prevent rain, snow, condensation, and water droplets from contacting the lamp as this may cause bulb failure and possible shattering.
- Quartz bulbs run with a high internal pressure more than atmospheric. Whilst the construction is inherently strong, there is a slight risk of the bulb shattering.
- Never look directly into an illuminated searchlight as this may cause severe damage to eyesight. If it is necessary to inspect a lamp whilst in operation, always wear suitable protective goggles.
- Should it be necessary to examine the lamp with the front bezel removed, always use a protective shield and wear goggles to ensure a safe working environment.
- Never attempt to clean a lamp whilst in use.
- Searchlights get hot. Never touch the unit when lit and always allow 15 to 20 minutes for cooling down after turning the searchlight off.
- Never place anything on or cover the searchlight when in use.
- Ensure the lamp has cooled sufficiently before removal.
- If undue force appears necessary to remove the lamp, the equipment should be inspected by a competent person or contact the manufacturer.
- When breaking a lamp for disposal, care must be taken to ensure the glass fragments are safely contained. This operation must be performed out of doors in free air. In all circumstances refer to the lamp manufacturer's instructions packed with the lamp.
- Due to the vast range of lamps available it may appear possible that more powerful lamps can be used in the equipment than for which it was designed. Even when the unit will physically accept a higher wattage or voltage lamp, this substitution is not recommended and is dangerous. This action will also void any warranties on the equipment.

Always refer to the lamp manufacturer's technical data when dealing with lamps.

3 - Technical Information

This product has been designed to operate in accordance with the product specification. The FH380RC Twin Head searchlight has the following features:

- All marine grade materials and fixings.
- Parabolic glass reflector.
- Powder coated & stove enamel paint finish.
- Instant lamp re-strike. No cooling down time required.
- Economical 1000-hour lamp life.
- 385° horizontal rotation.
- Vertical movement +30° to -35°.
- Variable speed 1-23°/sec (Pan), 1-8°/sec (Tilt).
- Remote focus facility.
- Heaters in the motor gearbox and searchlight head.
- Toughened super clear Optiwhite front glass.
- Luminous flux 110,000.
- Colour temperature 6,800K.
- RS485 connectivity & auto home positioning.
- Variable Speed LED Joystick panel, Dimmable.
- Searchlight Weight 85Kg.
- Control Gear Weight 23Kg each.
- Sealing – IP66 Gearbox, IP56 Searchlight & PSU IP66.

The searchlight also performs to the following optical data:

- | | |
|---------------------------------------|---------------------------------------|
| ■ Supply voltage | 240v |
| ■ Wattage | 1200w |
| ■ Peak Beam Candlepower | 33,700,000 Lux with standard glass |
| ■ Peak Beam Candlepower | 26,960,000 Lux with ultraviolet glass |
| ■ Range | 5,805 metres (standard glass) |
| ■ Range | 4,644 metres (ultraviolet glass) |
| ■ Divergence | Spot 2° to Flood 10° |
| ■ Operational temperature with heater | -50°C |

In order that the searchlight operates correctly it is imperative that competent personnel are responsible for the installation, operation, and servicing of this equipment. Failure to adhere to this advice may cause premature failure or incorrect operation of the searchlight, which may damage the equipment or cause personal injury.

4 - Unpacking and Installation Instructions

The following instructions should be read and fully understood prior to installing the equipment to ensure that the correct procedures are followed, and all safety precautions are observed.

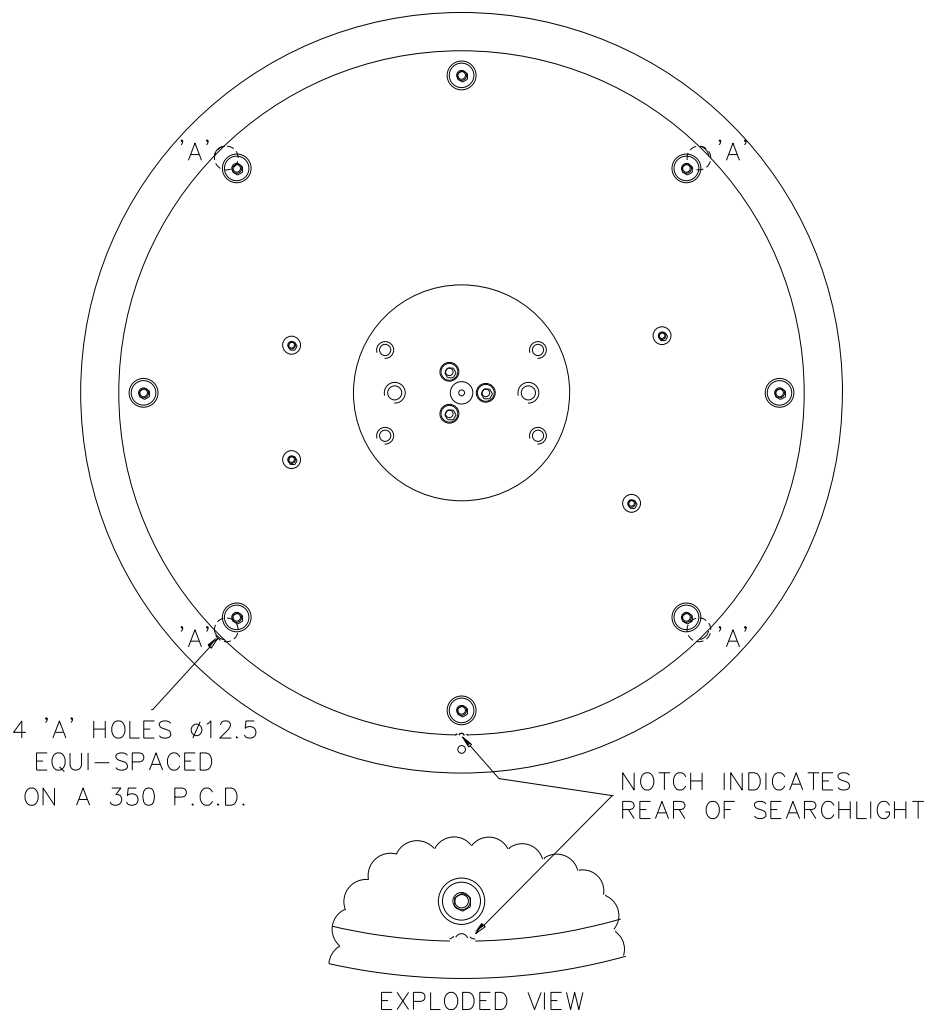
Note: If the equipment has been in storage for a considerable amount of time, it is advisable to conduct a routine maintenance check on all parts before installation.

Safety Precautions

This equipment should not be connected to an electrical supply before being installed. Installation procedures should be adhered to, to ensure a safe working environment and reduce the risk of damage or personal injury.

Preparing the Mounting Position

Mark out and drill the fixing holes through the deck (refer to drawing C21501). If anti-vibration mounts are to be fitted, the fixing holes for the mounts should also be marked out and drilled. Prior to manoeuvring the searchlight into its' fixing position, the AV mounts should be fitted to the base. When in the desired position, bolt the searchlight firmly down. On an uneven surface it may be necessary to use a suitable sealant such as silicone, to ensure a weatherproofed joint.



5 - Electrical Installation

Note: ~

When the main power is first applied to the searchlight, the searchlight will carry out a self-test, it will Pan to the left limit and Tilt down to the limit, once this is complete, the searchlight will then move to the centre and horizontal, during this please do not try and operate the searchlight while this test is being carried out. Once the searchlight is back at centre the searchlight can then be operated normally, by pressing the 1/0 button on the control panel.

For safety purposes, only competent personnel should perform the electrical installation. All equipment should be installed to current Electrical Regulations and Standards.

To obtain the maximum light output from the searchlight, it is essential that the full operating voltage of the lamp fitted be applied to the lampholder contacts.

Method of Electrical Connection

- 1) Disconnect the supply before working on the electrical system.
- 2) The searchlight must be connected to a fused electrical supply, using suitably sized cable.
- 3) If the searchlight is located a considerable distance from the supply, provision must be made in the cable size to overcome the voltage drop.

The following table below indicates the maximum length of cable to be used for the AC supply cable (Butyl HO7 RN-F) to the Junction Box:

Searchlight	240v 1200w
Cable Size (mm ²)	Distance Max
1.5	62 MTRS
2.5	101 MTRS
4.0	160 MTRS
6.0	249 MTRS
10.0	417 MTRS

- 4) Whenever possible cable terminations should be made below deck and with approved terminal devices.
- 5) If a spare auxiliary fuse or circuit breaker is not available, one of the correct type/ratings should be fitted and connected to a positive supply. It is advisable to locate a bus bar or main connection and avoid any direct connection to the supply:
- 6) For 220v AC products, the following colour coding system should be used for the customer supply cable:

Brown	- Live
Blue	- Negative
Green/Yellow	- Earth

Installation Guidelines

A typical installation and connection routine for the FH380RC searchlight is as follows:

Referring to wiring diagram C29454 a supply is fed to the junction box, which then provides a common feed to the control gear, motor gearbox, searchlight, and joystick panel.

The searchlight has been pre-wired with 3 meters of cable from the motor gearbox to the junction box provided. The searchlight heads are pre-wired along with the connecting cable to the motor gearbox.

Cables required to be connected by the customer: -

2 pair twisted 0.22mm 100ohm screened cable from the joystick panel to the junction box.

5 core 1.5mm cable from both control gear to the junction box.

Supply cable to the junction box.

6 - Operating Instructions

This equipment is designed for use out of doors, in free air. Never place anything on or cover the searchlight when in use as this may present a hazard.

Switch On

The panel is activated using the 1/0 button. This will illuminate brightly when the panel is active.

Lamp Control

When the panel is active pressing the LIGHT, button will switch the lamp on or off.
If the control panel is switched off with the 1/0 button the lamp will switch off.

Focus Control

The lamp focus can be adjusted using the FOCUS button. Lamp focus will adjust continuously whilst FOCUS is pressed.

Beam Direction

The beam direction can be adjusted using the joystick when the panel is active. Moving the joystick left or right will pan the beam clockwise or anticlockwise.
Moving the joystick up or down will move the beam up or down. The speed of movement is proportional to the movement of the joystick. It is possible to move the beam in both directions at once by moving the joystick diagonally.

Home

The lamp can be returned to a pre-set home position. By default, this is dead ahead with the beam level although different positions can be programmed as described below.

Set New Home Position

To set a new home position move the lamp to the new desired home position. Switch the panel off then press the joystick down to its limit and press the lamp 1 button. The current position will now be the new home position.

Set Motion Limit (only available when Remote Focus is fitted)

The lamp travel can be limited in either axis and either direction. To set a new limit, switch the panel on and move the lamp to the desired limit position. Switch the panel off then press and hold the focus 1 button whilst moving the joystick full travel in the direction of the desired limit. Hold in this position for 4 seconds. For example, to set a limit to the tilt up motion; -

1. Switch panel on and drive the searchlight to the desired tilt up limit position.
2. Switch panel off.
3. Press and hold the FOCUS 1 button and hold joystick in the full up position for 4 seconds.
4. Tilt up motion will now be inhibited above the current position.

Clear Motion Limits

Motion limits as set above can be cleared by switching the panel off then pressing and holding the focus 1 button and lamp 1 buttons together for 10 seconds.

Adjusting Panel Illumination

The panel illumination intensity can be adjusted to suit ambient light levels. To adjust the intensity, switch the panel on then switch it off with the 1/0 button and keep the 1/0 button pressed. To increase intensity, move the joystick to the right. To decrease move to the left. Note that the 1/0 button must be kept depressed whilst the joystick is moved. All indicators will illuminate whilst adjustments are performed. Adjustment is complete when the 1/0 button is released.

Obtaining Fault Status

Fault codes can be accessed by switching the control panel on with the 1/0 button and keeping the 1/0 button pressed for 10 seconds. Fault codes are indicated by the 1/0 button flashing a number of times related to the fault. Fault codes are detailed below. If more than one fault is present the 1/0 button will indicate them in sequence.

1. Pan Limit. – Either of the pan limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
2. Tilt Limit. – Either of the tilt limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
3. Pan motor over current. – The pan motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
4. Tilt motor over current. – The tilt motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
5. Focus motor over current. – The focus motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
6. FBUS interface over current. – The speed control card supplies 24VDC to the remote-control panels. This fault indicates the 24VDC output is taking excessive current. The FBUS supply output will switch off. To restore this output, remove the supply from the speed control card for a period.

7. Anti-condensation heater output over current. – The 24VDC anti condensation heater output is taking excessive current. The heater output will switch off. To restore this output, remove the supply from the speed control card for a period.
8. Limit Switch Error. Some lamp types do not use all or some limit switches. If an invalid limit switch input is detected it is probable the speed control card is set to the wrong product or there is a wiring error.
9. Datum Error. The start-up datum system has not completed correctly.
10. Product type not set or corrupt. The product type has not been set, has been set incorrectly or is corrupt.
11. Supply voltage out of tolerance. The 24V supply is outside the range 18-30V.



FBUS SPEED CONTROL ASSEMBLY DETAILS

MAINS CONNECTORS

L Live.
N Neutral
E Earth

TILT CONNECTOR

MR Tilt Motor Red Wire (+)
MB Tilt Motor Black Wire (-)
ER Tilt Encoder Red Wire (5V). (Voyager Brown Wire)
EG Tilt Encoder Green Wire (Phase A Output) (Voyager Yellow Wire)
EW Tilt Encoder White Wire (Phase B Output)
0V Tilt Encoder Black Wire (Voyager Blue Wire)
Tilt Limit Switch Common Black Wire
UL Tilt up Limit Switch Orange Wire
DL Tilt down Limit Switch Blue Wire

PAN CONNECTOR

MR Pan Motor Red Wire (+)
MB Pan Motor Black Wire (-)
ER Pan Encoder Red Wire (5V)
EG Pan Encoder Green Wire (Phase A Output)
EW Pan Encoder White Wire (Phase B Output)
0V Pan Encoder Black & Pan Limit Switch Common
CL Pan Clockwise Limit Switch Orange Wire (As viewed looking down on lamp)
AL Pan Anticlockwise Limit Switch (As viewed looking down on lamp)

HEAD CONNECTOR

0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
H Heater Active High Output
F Focus Motor Active High Output
FP Focus position potentiometer

HEAD 2 CONNECTOR

0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
FP Focus position potentiometer
F Focus active high 5v output
L Lamp active high 5v output
24 24v supply out

FBUS CONNECTOR

0 0V out to Joystick Panels
T Line Terminate (Connect to + for terminate)
+ FBUS Data +
- FBUS Data -
24 24V Supply out to joystick panels

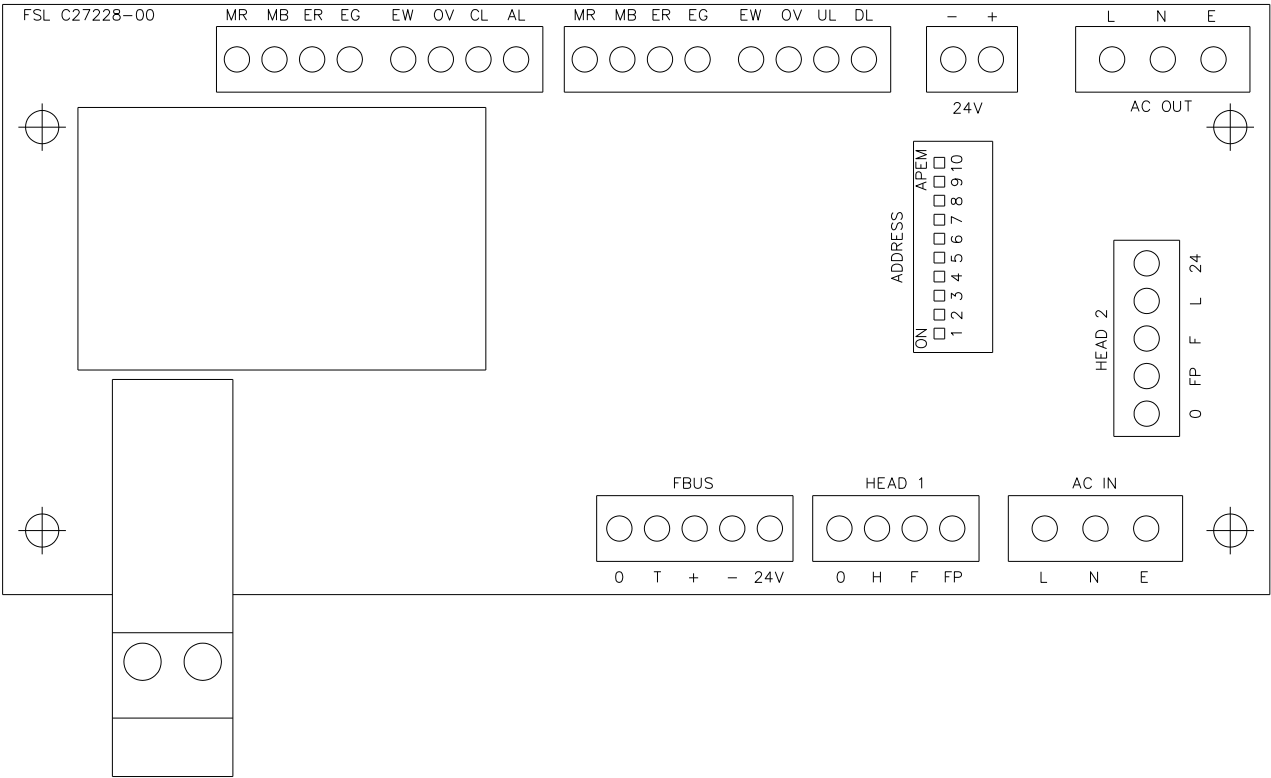
24 VOLT INPUT

- Negative
- + Positive

LAMP RELAY

- Relay input
- Relay output

FBUS Speed Control Board



FBUS EXTENSION CONTROL BOARD DETAILS

HEAD CONNECTOR

- 0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
- H Heater Active High Output
- F Focus Motor Active High Output
- FP Focus position potentiometer

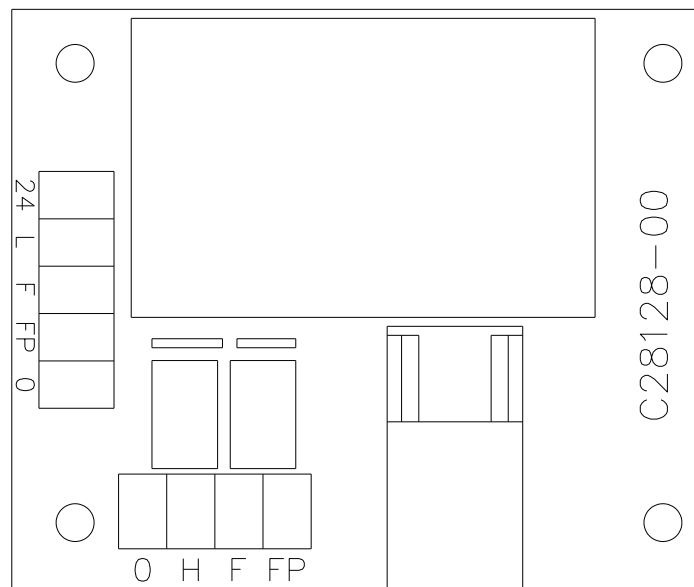
HEAD 2 CONNECTOR

- 0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
- FP Focus position potentiometer
- F Focus active high 5v output
- L Lamp active high 5v output
- 24 24v supply out

LAMP RELAY

- Relay input
- Relay output

FBUS Extension Control Board



CONNECTIONS TO FBUS JOYSTICK CONTROL PANEL

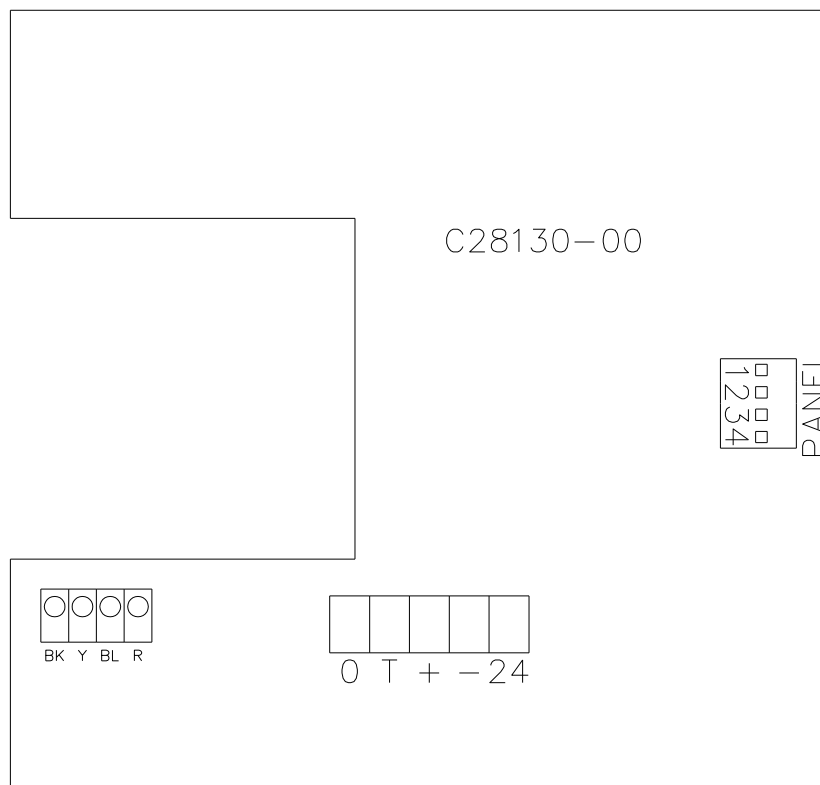
FBUS CONNECTOR

0	OV Supply Input
T	Line Terminate (Connect to + for terminate)
+	FBUS + RS485 Data In/Out
-	FBUS - RS485 Data In/Out
24	+24V Supply Input

JOYSTICK CONNECTOR

BK	Joystick Black Wire
Y	Joystick Yellow Wire
BL	Joystick Blue Wire
R	Joystick Red Wire

FBUS JOYSTICK CONTROL BOARD



FBUS ADDRESS SWITCHES

OVERVIEW

FBUS uses two types of address switch. One type is rotary, and the value selected is the value shown on the dial. The other type is rows of switches whose operation is described below: -

The switches all operate in the same manner producing a binary value with the highest binary value to the left and the lowest value to the right. The values for each switch are listed below: -

SPEED CONTROL CARD LAMP ADDRESS

SWITCH NUMBER	VALUE
SWITCH 10	1
SWITCH 9	2
SWITCH 8	4
SWITCH 7	8
SWITCH 6	16

FBUS DATA PROTOCOL

OVERVIEW

The Francis bus (FBUS) is a custom communication protocol based on RS485 two wire bi-directional communication hardware. The system provides a simple bi-directional link between lamps and lamp control panels. The system allows given panels to communicate with different lamps and also allows a number of panels to communicate with the same lamp.

DETAILED DESCRIPTION

The FBUS system runs at 38.4K Baud. This low data rate facilitates longer cable runs and complements the fairly small amount of data transfer required whilst still providing a fast response. The data frame is 11 bits with 9 data bits, one start and one stop bit. A simple error detection system is employed which is described in detail later. Data is sent LSB first.

To prevent data collisions the system uses a polling technique. Lamp number 0 is the default bus master and controls timing of all communications by polling other units connected to the bus. If lamp 0 is not operating or powered down, lamp 1 automatically becomes the bus master as will lamp 2 if lamp 1 is not operating.

The system differentiates between address and data values by setting data bit 8 high for an address. Panel 2 address would therefore be sent as hex 102 or binary 100000010. The lamps and panels use different address ranges with panels being addresses 0-15 and lamp addresses starting at 16 and going up to 56. A lamp whose address was set to 0 on the address switches will actually be address 16 and would be transmitted as hex 110 or binary 100010000.

If lamp 0 is active this becomes the bus master and sequentially transmits the full address range. No other units will transmit until they receive their address. Each address is followed by a 1mS dead period where the master switches from transmit to receive and monitors the bus for activity. If activity is present the master will not transmit the next address until 1mS after bus activity ceases. After the full panel address range has been sent (addresses 0-15) the master starts to send lamp addresses.

These operate slightly differently in that, if more than three successive addresses do not illicit a response, the bus master will assume the last lamp has been polled and re starts the data cycle by reverting to panel address 0. When a remote panel receives its address, it will send data if it has any to send, if not, no data will be sent. Lamps operate differently in that they will always send data after they have seen their address on the bus. Panels can send data to any lamp therefore they transmit a modified lamp address value prior to the lamp command(s). The modified address is received by lamps and, if it matches their own address, the command(s) which follow will be received and processed.

A detailed description of panel and lamp data follows.

PANEL TRANSMITTED DATA

Panels only send data when there is data to be sent i.e., there has been activity at the panel which must be sent to a given lamp. If there is no data to be sent, a panel will not transmit. The amount of data a panel sends will depend upon the amount of activity at the panel and can be 2 to 10 bytes. The commands described below are sent after a panel receives its address which it uses as indication that it has a transmit time slot. Before any commands are sent the panel must define which lamp the data pertains to. This is achieved by preceding the command with a lamp address. Note that bit 7 is not set when a panel defines the lamp to which it is to transmit. Lamps recognise the address and receive data when the address matches their own. To send commands to lamp number 2 a panel would precede the lamp command(s) with the address value Hex 2, Binary 000000010. It is important to note that multiple commands must be sent in numerical order i.e., a command with value 01 must be sent before a command with 06 etc.

Panel transmit commands are listed below; -

DATA_PAN_JOYSTICK (Hex 01)

This is a two-byte command and must be immediately followed by another byte whose value determines the lamps direction and speed. The value is centred on 128 and has a range of 128 +/- 64. A value of 130 will make the lamp rotate slowly clockwise. Increasing the value will make the lamp move faster. A value of 126 will make the lamp rotate slowly anticlockwise. Decreasing the value will make the lamp move faster. Transmitting values 01 then C0 would make the lamp pan clockwise at full speed.

DATA_TILT_JOYSTICK (Hex 02)

This is a two-byte command and must be immediately followed by another byte whose value determines the lamps direction and speed. The value is centred on 128 and has a range of 128 +/- 64. A value of 130 will make the lamp point upwards slowly. Increasing the value will make the lamp move faster. A value of 126 will make the lamp move down slowly. Decreasing the value will make the lamp move faster. Sending values 02 then C0 would make the lamp tilt up at full speed.

DATA_LAMP_BUTTON (Hex 0A)

This is a single byte command. The same command is sent to switch the lamp on or off. This command must only be sent once for each press of the button. Sending again will switch the lamp again. Basically, if the lamp was off, sending this value will switch it on. If the lamp was on, sending this value will switch it off. This technique is employed to facilitate simultaneous lamp control from a number of different panels. Basically, what is sent is just information that the lamp on off button has been pressed. How the lamp reacts to this depends on the lamp's current status. Most of the other lamp button commands operate in a similar manner except the focus button. Confirmation that the command has been received can be obtained by reading the lamp status byte described below.

DATA_FOCUS_BUTTON (Hex 0B)

This is a single byte command. When the lamp receives this, it will run the focus motor as long as the command remains. A panel will send this command so long as the focus button is pressed.

DATA_HOME_BUTTON (Hex 0C)

This is a single byte command. A lamp receiving this will automatically move to the pre-set home position. The command does not need to be maintained while the lamp moves to home.

DATA_RECORD_BUTTON (Hex 0D)

This is a single byte command. The first time a lamp receives this command it will enter record mode and start monitoring all movement and lamp switching information. Recording will continue until the command is received again when it will stop recording. As with most of the button commands it is essential this command is just sent once. Confirmation that the command has been received can be obtained by reading the lamp status byte described below.

DATA_PLAY_BUTTON (Hex 0E)

This is a single byte command. The first time this is received a lamp will start playing back any movement / lamp switching activities which were recorded using the record function above. This will continue until the command is received again or the lamp receives a move command (DATA_PAN_JOYSTICK or DATA_TILT_JOYSTICK).

DATA_HOME_LP (Hex 0F)

This is a single byte command which activates when the home button is pressed and held for 5 seconds (Home Long Press). This is used to store a new home position. A lamp receiving this command will store the current position as the value to move to when the home button is pressed normally. Note that a lamp can only receive up to 10 bytes at a time. A panel's transmit sequence is the modified receiving lamp address followed by data commands then the CRC. The CRC is formed by the sum of all the commands + the lamp address value – note however that the address value used in the CRC is the unmodified value (Bit 7 clear).

DATA_PAN_POSITION (Hex 18)

This is a three-byte command. Following the DATA_PAN_POSITION command two data bytes specify the position to which the lamp must move. The bearing resolution is 0.1 degrees. The value is sent LSB first with the first byte representing the lower position command bits. The MSB (sent last) lower 4 bits represents the remaining value. The position value is centred on 2048 (Binary 1000 0000 0000) so a value of 2048 would make the lamp move to the dead ahead position. An increasing value represents a clockwise motion with a resolution of 0.1 degrees. A value of 2058 would therefore represent 1 degree clockwise (2058 = 2048 + 10 – but resolution is 0.1 degrees so a value 10 = 1 degree). Values below 2048 represent anticlockwise motion so a value of 1048 would represent an angle 100 degrees anticlockwise of centre.

DATA_TILT_POSITION (Hex 19)

This is a three-byte command. Following the DATA_TILT_POSITION command two data bytes specify the position to which the lamp must move. The bearing resolution is 0.1 degrees. The value is sent LSB first with the first byte representing the lower position command bits. The MSB (sent last) lower 4 bits represents the remaining value. The position value is centred on 2048 (Binary 1000 0000 0000) so a value of 2048 would make the lamp move to the dead ahead position. An increasing value represents tilting up with a resolution of 0.1 degrees. A value of 2058 would therefore represent 1 degree up from dead ahead ($2058 = 2048 + 10$ – but resolution is 0.1 degrees so a value 10 = 1 degree). Values below 2048 represent tilting down so a value of 1748 would represent an angle 30 degrees down from centre.

LAMP TRANSMITTED DATA

A given lamp after it receives its normal address (Hex 110 to Hex 138) will always send the following data in this specific order. The lamp must transmit its first data byte (pan position) within 1mS of receiving its standard address and the gaps between successive bytes must be less than 1mS.

Lamp TX Byte 1 – Pan position LSB
Lamp TX Byte 2 – Pan position MSB
Lamp TX Byte 3 – Tilt position LSB
Lamp TX Byte 4 – Tilt position MSB
Lamp TX Byte 5 – Lamp status
Lamp TX Byte 6 – CRC

Each byte is described below

Pan Position

This is a 12-bit value with lamp pointing straight ahead being a value of 2048 and the value increasing as the lamp rotates clockwise as viewed from above. The system has a resolution of 0.1 degrees so 90 degrees clockwise from centre would be a value of 2948 ($2048 + 900$).

Tilt position

This is a 12-bit value with lamp horizontal being a value of 2048 and the value increasing as the lamp beam points up. This has a resolution of 0.1 degrees.

Lamp Status

This is an 8-bit value with each bit representing a specific status aspect. The bit functions are listed below; -

Bit 0 - Lamp on
Bit 1 - Pan Limit reached
Bit 2 - Tilt Limit reached
Bit 3 - Lamp Recording
Bit 4 - Lamp Playing
Bit 5 - Lamp Overheated
Bit 6 - Lamp moving to home
Bit 7 - Reserved

The bits are all true logic so if the lamp is switched on, bit 0 will be high.

CRC

The CRC is a simple data checking system. Basically, this is just the sum of the lamps address and bytes above. The value is radix to 8 bits. If the lamp address was 0 (bus address value 16) and the pan and tilt were both at centre and the lamp was switched on and all other status bits were 0 the values would be Hex 110, 80, 80, 01. This would give a CRC value of 11.

Each lamp connected to the bus will always send the data sequence above after it detects its address on the bus. This is basically broadcast information which will be picked up by any panel whose lamp address value matches the currently transmitting lamp address. In this way a panel, which can access more than one lamp, will always update to reflect the status of the currently selected lamp more or less instantly.

EXTERNAL INTERFACE TO LAMPS

Interfacing to FBUS is simple. Any external interface must act as a slave and only send data when given an address slot. The address of an external interface can be any of the panel addresses providing these are not in use by other panels connected to the bus. To receive data from a lamp simply wait for the specific lamps address to be present on the bus then load the next six bytes which will comprise the lamps transmitted data as described above. A detailed description of transmitting and receiving is described below.

TRANSMITTING TO A LAMP

Basically, any sending device mimics a control panel. The full range of panel transmit commands, as described above, can be employed. Data can be sent to any lamp on the system. Two transmit examples are listed below.

EXAMPLE 1

Sending a lamp on/off command using panel 0 address and sending to lamp address 0. Note that the lamp will change switched state each time this command is sent therefore this should only be sent once.

1. Wait for panel address 0 (Hex 100) to be received from the bus.
2. Transmit lamp 0 address (Hex 110) within 1mS. Lamp address 0 is physical address 16 (Hex 10). When a panel sends to a lamp bit 8 is set (hex 100).
3. Send DATA_LAMP_BUTTON Command (Hex value 0A) within 1mS.
4. Send CRC value, in this case Hex 110 + Hex 0A = 11A after radix to 8 bits = 1A. This completes the transmission

EXAMPLE 2

Sending a half speed pan clockwise command using panel 1 address and sending to lamp address 6. – Note that in this example the lamp will continue to pan as long as the command is repeated.

1. Wait for panel address 1 (Hex 101) to be transmitted by the master.
2. Transmit lamp 6 address (Hex 16) within 1mS. Lamp address 6 is physical address 22 (Hex 16).
3. Send DATA_PAN_JOYSTICK Command (Hex value 01) within 1mS.
4. Send pan value half speed = $128 + (64/2) = \text{Hex A0}$ within 1mS.
5. Send CRC value, in this case Hex 116 + Hex 01 + Hex A0 = 1D7 after radix to 8 bits = B7.
6. This completes the transmission

RECEIVING FROM A LAMP

Lamps broadcast data sequentially. There is no need to actively request data to be sent, just wait for the lamps address with bit 7 set to be present on the bus and load the next six bytes. An example is given below; -

EXAMPLE

Obtain lamp number 2 pan position.

1. Listen to the data bus and wait for value Hex 112. (Lamp addresses start at hex 10 so lamp 2 is value 12. Addresses always have bit 8 set so total value is Hex 112).
2. Load the next six bytes from the bus.
3. If desired check the last of the six bytes which is the CRC.
4. Read the two bytes which will be a value centred on 2048 increasing for clockwise from centre and decreasing for anticlockwise. This is lamp number 2 current pan position.

FBUS Speed Control Assembly Status LED Operation

Overview

The FBUS motor control card has a status LED near the top of the card (labelled 'STATUS'). This has a number of functions as detailed below.

SOFTWARE VERSION

When power is applied to the speed control card the status LED will flash green. The number of flashes corresponds to the software version.

FBUS NORMAL OPERATION

When the system is operating from FBUS the status LED will illuminate static green. When a valid FBUS data signal is received the LED will switch off momentarily to indicate data reception. If data is continuous the LED will flash green slowly.

DMX NORMAL OPERATION

When the system is operating from DMX the status indicator will flash green slowly when DMX data is present. If no DMX data is present the LED will be static green.

OPERATION DURING FAULTS

During faults normal status LED operation is overridden. The status LED will flash red. The number of flashes corresponds to the specific fault. If there are multiple faults the LED will flash accordingly with a gap between each fault flash sequence. Fault details are provided below with the number of flashes indicated on the left.

1. Pan Limit. – Either of the pan limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
2. Tilt Limit. – Either of the tilt limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
3. Pan motor over current. – The pan motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
4. Tilt motor over current. – The tilt motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
5. Focus motor over current. – The focus motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
6. FBUS interface over current. – The speed control card supplies 24VDC to the remote-control panels. This fault indicates the 24VDC output is taking excessive current. The FBUS supply output will switch off. To restore this output, remove the supply from the speed control card for a period.
7. Anti-condensation heater output over current. – The 24VDC anti condensation heater output is taking excessive current. The heater output will switch off. To restore this output, remove the supply from the speed control card for a period.
8. Limit Switch Error. Some lamp types do not use all or some limit switches. If an invalid limit switch input is detected it is probable the speed control card is set to the wrong product or there is a wiring error.
9. Datum Error. The start-up datum system has not completed correctly.
10. Product type not set or corrupt. The product type has not been set, has been set incorrectly or is corrupt.
11. Supply voltage out of tolerance. The 24V supply is outside the range 18-30V.

FBUS INTERFACE UNIT (if supplied)

OVERVIEW

Francis Searchlights FBUS system is designed to allow multiple control panels to manage a number of searchlights on a common data cable. The data system is application specific and, as such, has a fixed data rate and complex timing. The FBUS interface offers a simplified and less time constrained communication interface to the FBUS system over a number of different physical layer communication standards and data rates.

POWER / CONNECTIONS

The interface draws a supply from the FBUS, no external power supply is required. The interface connects to the four-wire FBUS system like any other FBUS system component. The four-wire interface provides a 24V supply and RS485 communications with FBUS.

Connection to the external interfaces will depend on the user's choice of communication system. RS422 (4-wire) RS485 (2-wire) and RS232 are all provided. The RS422 OUT / IN legend on the PCB refers to the data direction from the perspective of the interface unit. The OUT terminals are the interface unit transmit connections. The RS232 connector is configured as a DCE and has all handshake lines looped. No flow control is required. The connections are listed below; -

1. Line signal detect (linked to pins 4 and 6)
2. TX out
3. RX in
4. DTE (linked to pins 1 and 6)
5. 0V
6. DCE Ready (linked to pin 1 and 4)
7. CTS (linked to 8)
8. RTS (linked to 7)
9. No Connection

OPERATOR INTERFACE

The operator interface is very simple with four buttons controlling a single layer menu system on a 2-line LCD display. A given menu item is selected with the SEL (select) button. If the menu item has an adjustable parameter this can be altered using the up and down arrow keys. The revised parameter is stored using the ENT (enter) button. A list of the menu items is provided below; -

MENU ITEMS

DEFAULT DISPLAY

The default display will be active from switch on until the select button is pressed. The default display has no adjustable parameters. The display top line shows the FBUS status. If FBUS is functioning correctly the display top line will show FBUS-ON. The top line of the display also shows the currently selected lamp status i.e., on or off. The default display will indicate if the currently selected lamp is active or not. If the FBUS is working and the currently selected lamp is responding the bottom line of the display will show the current pan and tilt angles.

SET PANEL ADDRESS

The FBUS interface looks like a standard control panel to the FBUS as such it must have a panel address. The panel address must not be set to the same value as any other panel on the system. Panel addresses start at 0 and go up to 15. Panel addresses should be sequential and start from zero. Once set pressing ENT stores the address.

SET LAMP ADDRESS

The interface unit has menu items (described below) which send commands directly to a given lamp. The default display described above displays data from a given lamp. The set lamp address item is used to define the 'given lamp' address. Lamp addresses start at 16 and go up to 40. This range equates to lamp 0-24 on the lamps address switches.

SET COMMS TYPE

This menu item selects the physical layer communication system for the external interface.

SET DATA RATE

This item selects the data rate for the external interface.

SET DATA CHECKING

This is used to enable or disable received data checking for the external interface. Switching data checking off can be useful during external interface development. Note that this does not affect data checking transmitted to the external interface from the interface unit and does not affect FBUS data checking.

SWITCH LAMP

This is one of the local functions included principally to aid external interface development and verify correct FBUS / lamp operation. Use the arrow keys to select lamp on or lamp off from line 2 of the display. Pressing ENT will send the on or off command to the currently selected lamp (see set lamp address).

SET PAN ANGLE

This command sends a move to pan position command to the currently selected lamp. The pan angle is set using the arrow keys. Pressing enter will make the lamp move to the displayed angle.

SET TILT ANGLE

This command sends a move to tilt position command to the currently selected lamp. The tilt angle is set using the arrow keys. Pressing enter will make the lamp move to the displayed angle.

FOCUS

This function is not implemented on all searchlights. Focus displays the current focus position with a value of 0-100. A value of 50 should represent the most focused beam with the beam diverging above and below 50. Note that the value will ascend from 0-100 the reset back to 0. Pressing the arrow up button will operate the focus motor.

FAULTS+LIMITS

This displays any faults or limit switch activation relating to the selected lamp. Multiple faults will be displayed sequentially.

LAMP SOFTWARE

This displays the software version of the currently selected lamp

LAMP TYPE No

This displays the lamp type number.

EXT COMMS DATA

This item is included to aid external interface development. The display bottom line will show any valid received commands preceded by the lamp number to which the command is sent. If data checking is enabled the display will indicate if there is a CRC error. The system will also indicate if there has been a bad lamp address or if the command sent is not valid.

FBUS SUPPLY

This just indicates the FBUS supply voltage. FBUS operates at 24V. Values above 30 or below 18 indicate something is wrong.

EXTERNAL DATA INTERFACE – RECEIVED COMMANDS

The external data interface uses command data packets with between four and six bytes including the CRC.

The system uses standard 8-bit data transfer with 1 start bit and 1 stop bit.

Data is sent least significant bit (LSB) first.

All data transfer is initiated by the user therefore the system will be inactive until a user transmission.

All data reception must start with a sync byte. The sync byte is value 0xFF.

The next byte is the lamp address. The lamp address is a value between 0x90 and 0xA8. Lamp 0 address would therefore be sent as 0x90. The lamp address indicates which lamp on the system the remaining data is to be directed to.

The next byte is the lamp command. Lamp commands are detailed below.

Some lamp commands have subsequent data bytes.

DATA_FOCUS (0x0B)

This is a four-byte command (Sync, Lamp address, command, CRC). A lamp receiving this will operate its focus motor momentarily. To keep the focus motor running the command must be sent repeatedly.

DATA_MOVE_TO_HOME (0x0C)

This is a four-byte command (Sync, Lamp address, command, CRC). A lamp receiving this will automatically move to the pre-set home position. The command does not need to be maintained while the lamp moves to home. If a home position has not been defined the home position will be straight ahead with the lamp horizontal.

DATA_STORE_HOME (0x0F)

This is a four-byte command (Sync, Lamp address, command, CRC). A lamp receiving this will store the current pan and tilt position values and will move to these values when the DATA_MOVE_TO_HOME command is issued.

DATA_PAN_CLOCKWISE (0x14)

This is a five-byte command (Sync, Lamp address, command, speed, CRC)
The speed value is between 0 and 127. Value 0 stops pan motion. Increasing values make the lamp move progressively faster. Transmitting codes 0xFF 0x90 0x14 0x7F would make lamp 0 move full speed clockwise.

DATA_PAN_ANTICLOCKWISE (0x15)

This is a five-byte command (Sync, Lamp address, command, speed, CRC)
The speed value is between 0 and 127. Value 0 stops pan motion. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x90 0x15 0x7F would make lamp 0 move full speed anticlockwise.

DATA_TILT_DOWN (0x16)

This is a five-byte command (Sync, Lamp address, command, speed, CRC)
The speed value is between 0 and 127. Value 0 stops tilt motion. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x92 0x16 0x7F would make lamp 2 move down at full speed.

DATA_TILT_UP (0x17)

This is a five-byte command (Sync, Lamp address, command, speed, CRC)
The speed value is between 0 and 127. Value 0 stops tilt motion. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x92 0x17 0x7F would make lamp 2 move up at full speed.

DATA_MOVE_TO_PAN_POSITION (0x18)

This is a six-byte command (Sync, Lamp address, command, position LSB, Position MSB, CRC). The position value is 12 bits and gives a resolution of 0.1 degrees. The most significant byte (sent last) comprises the top 5 bits. The most significant bit (bit 4 – 0b0000x000) determines whether the pan angle is positive (clockwise of centre) or negative (anticlockwise of centre) Bit 4 set to 1 indicates angle is clockwise. The remaining bits will increment as the lamp moves from centre in either direction. The least significant byte comprises the lower 7 bits of the value with the most significant bit set to zero. As an example, a value of 0x0A followed by 0x08 would indicate an angle 1 degree clockwise of centre. 0x0A = 10 but resolution is 0.1 degrees so divide integer value by 10 to give 1.0 degrees. A value of 0x64 followed by 0x00 would indicate a value of 10 degrees anticlockwise of centre.

DATA_MOVE_TO_TILT_POSITION (0x19)

This is a six-byte command (Sync, Lamp address, command, position LSB, Position MSB, CRC). The position value is 12 bits and gives a resolution of 0.1 degrees. The most significant byte (sent last) comprises the top 5 bits. The most significant bit (bit 4 – 0b0000x000) determines whether the tilt angle is positive (tilted up relative to straight ahead) or negative (tilted down relative to straight ahead). Bit 4 set to 1 indicates angle is tilt up. The remaining bits will increment as the lamp moves from centre. The least significant byte comprises the lower 7 bits of the value with the most significant bit set to zero. As an example, a value of 0x0A followed by 0x08 would indicate an angle 1 degree up of centre. 0x0A = 10 but resolution is 0.1 degrees so divide integer value by 10 to give 1.0 degrees. A value of 0x64 followed by 0x00 would indicate a value of 10 degrees down of centre.

DATA_LAMP_ON (0x1A)

This is a four-byte command (Sync, Lamp address, command, CRC). The lamp will switch on when this code is received.

DATA_LAMP_OFF (0x1B)

This is a four-byte command (Sync, Lamp address, command, CRC). The lamp will switch off when this code is received.

DATA_RECORD (0x0D)

This is a four-byte command (Sync, Lamp address, command, CRC). The lamp will start recording motion and lamp on / off data when this code is received.

DATA_PLAY (0x0E)

This is a four-byte command (Sync, Lamp address, command, CRC). The lamp will start playing back a previously recorded sequence when this code is received.

DATA_REQUEST_LAMP_STATUS (0x1E)

This is a four-byte command (Sync, Lamp address, command, CRC). When the interface receives this command, there is a 10mS delay then the interface will switch to transmit and send 13 bytes as detailed below.

1. Sync (FF)
2. Lamp Address with bit 7 set - range 0x90-0xA8
3. Pan Position LSB (Same format as pan position command above)
4. Pan Position MSB
5. Tilt Position LSB (Same format as tilt position command above)
6. Tilt Position MSB
7. Lamp Status
 - Bit 0 - Lamp on
 - Bit 1 - Pan Limit reached
 - Bit 2 - Tilt Limit reached
 - Bit 3 - Lamp Recording
 - Bit 4 - Lamp Playing
 - Bit 5 - Lamp Overheated (not currently implemented)
 - Bit 6 - Lamp moving to home

8. Focus position - Value between 0 and 100 - finest focus at value 50.

9. Fault Status 1

- Bit 0 - Pan motor current high.
- Bit 1 - Tilt motor current high.
- Bit 2 - Focus motor current high.
- Bit 3 - FBUS +24V out current high.
- Bit 4 - Heater current high.

10. Fault Status 2

- Bit 0 - Limit switch error.
- Bit 1 - Datum error.
- Bit 2 - Lamp type invalid.
- Bit 3 - Supply voltage out of tolerance.

11. Lamp software version.

12. Lamp type No.

13. CRC

ERROR CONTROL

Error control is supported by a CRC following each data packet. The CRC is radix to 7 bits with a value between 0 and 127. The CRC is simply the addition of all packets data values including the address and start byte (0xFF). For example, if lamp 0 were commanded to run its focus motor the transmitted data would be 0xFF, 0x90, 0x0B. The addition of these values gives 0x19A. The CRC would therefore be this value radix to 7 bits to give a value of 0x1A. this value is the CRC and would be sent as the last byte of the packet.

DATA TIMING

Data packets can be sent up to 10 times per second. Each packet starts with the lamp address which is the only value with bit 8 set. The remaining bytes should follow immediately. The whole packet must be received within 30mS. A packet lasting longer than 30mS will be rejected.

There is no minimum packet send rate. If there is no new data, the system will remain idle.

When the interface unit receives the DATA_REQUEST_LAMP_STATUS command there is a 2-30mS delay after which the interface will switch to transmit and output the 5 data bytes in direct succession. After the last byte has been sent the interface will switch back to receive almost immediately.

7- Fault Finding

All fault finding must be conducted by a competent person or qualified Electrical Engineer.

Failure of Lamp to light

Causes:

- 1) Power not supplied.
- 2) Fuse blown.
- 3) Failed lamp.

Remedy:

- 1) Check voltage at supply. If supply is not present the fault is at the customer supply. If power is present, see remedy 2.
- 2) Check fuse for visual failure. If non noticeable check fuse for continuity using a multi-meter. If fuse found to be faulty, replace with new part and test equipment again for correct working order. If found to be working correctly see remedy 3.
- 3) Firstly, check supply at lampholder connecting block (within searchlight barrel). If supply is present, disconnect unit from power supply before removing the lamp.

Failure of Remote Focus

Causes:

- 1) Power not supplied.
- 2) Faulty connections.
- 3) Failed motor

Remedy:

- 1) Check voltage at supply. If no supply present fault is at customer supply. If power is present, see remedy 2.
- 2) Check all wiring connections on motor and terminal rail, in accordance with the wiring diagram. If found to be correct, see remedy 3.
- 3) Remove focus motor and apply 24v DC directly across terminals. If motor does not rotate the unit has failed. A new focus motor should be fitted to the lampholder assembly.

NOTE: If a fault occurs on the pan and tilt gearbox, the unit should be returned to Francis Searchlights Limited for fault evaluation and repair.

8 - Maintenance and Servicing

To prolong the service life and performance of your searchlight, the following maintenance guidelines are recommended:

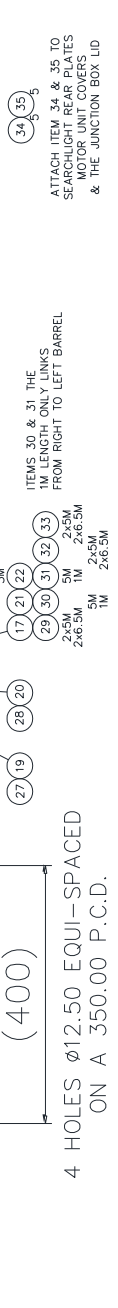
- Maintenance checks should be conducted before every voyage or at least every three months.
- Before checking, disconnect the equipment from the supply.
- Visually inspect the condition of the equipment.
- Any major or minor structural damage should be rectified immediately to reduce sympathetic wear.
- After inspection it may be necessary to clean the inside of the searchlight. The following procedure should be adhered to:
 - Remove the front bezel.
 - Clean the front glass inside and out using a proprietary glass cleaner.
 - Clean the reflector if required.
 - Check the reflector mounting gaskets. If signs of corrosion or damage are evident replace as necessary.
 - Ensure that the lampholder is free from corrosion or other damage.
- It is advisable to check all seals and gaskets for signs of degradation. Renew if necessary.
- Upon completing all maintenance requirements, the searchlight should be tested for full working order (approximately 20 minutes).

If in any doubt as to the correct servicing procedures to adopt, please contact your distributor/agent or the manufacturer who will be able to advise the best course of action for your product.

9 - Wiring Diagram & General Assembly

Drawing Number	Description
A7210	FH380RC 1200w 240v Twin Head General Assembly
C29454	Wiring diagram
C28070	Joystick Panel Assembly
C26961	Control Gear Assembly
C29435	Junction Box Assembly

50	C10554	M6 S/C SPRING WASHER	6
51	C04376	M4 PLAIN WASHER	2
52	C08793	M4 S/C SPRING WASHER	2
53	C12355	M10 NYLOC NUT	1
54	C06267	M6 FULL NUT	6





Francis BEARLIGHTS

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C29135	SHT
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PART No./DRG No.

SSYN BOX AJUNCTION

DESCRIPTION	

FINISH

SERIAL

8062 CT10	MATE
8062 CT8	

Sand Casting: To ISO
Die Casting: To ISO

General: \pm

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10 - Spare Parts List

The following spare parts can be ordered directly from the manufacturer:

Part Number	Description
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Searchlight Spares

D15746	1200w Lamp
C09868-00	G38 Lamp Holder
C22790-01	Fan
C08919-00	Front Glass
C24872-00	Ultraviolet Glass
C22011-00	Bezel Gasket
C08885-00	Reflector
C16880-00	Igniter
C28025-01	Focus Motor
C20281-00	Bellows
C27288-01	Heater

Motor Gearbox Spares

C27288-01	Heater
C27308-01	Pan Motor Sub Assembly
C27157-00	Tilt Motor
C22380-00	Micro switch no lever
C22382-00	Micro switch with lever
C27556-00	24v Power Supply Unit
C27187-01	Speed Controller PCB
C28128-00	Dual Head Extension PCB
C22381-00	Pedestal Top Sealing Gasket
C26441-00	Pedestal Cover Gasket

Control Gear

C23496-00	Ballast
C26986-00	MCB
C20235-00	Capacitor

Joystick Panel

C26537-00	Joystick
C28130-00	Dual Control Joystick PCB
C28151-00	Illuminated Push Button
C28150-00	Clear Plastic Lens
C27435-00	5-Way Connector

To prolong the life and performance of your product, we recommend that you only specify Francis Searchlights spare parts. This will ensure that any warranties on your equipment will not be invalidated.

When ordering spare parts please contact the Sales Department at Francis Searchlights Limited. Please always quote searchlight model and serial number. This will enable a fast response to your spares' requirements.