



User Instruction & Installation Manual

L300 Remote Control Twin Head



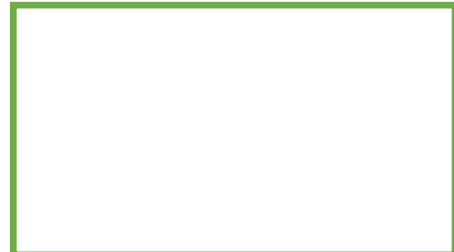
Product Reference Number:

A7177 - L300RC 468w LED 110/240v

Manufacturer's details:

Francis Searchlights Ltd
Union Road, Bolton
Lancashire, BL2 2HJ, UK
Tel: +44 (0) 1204 558960
Fax: +44 (0) 1204 558979
<http://www.francis.co.uk>
E-mail: sales@francis.co.uk

Distributor details:



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1 - Introduction

It is imperative that this manual is read carefully and understood before installing your equipment. For your future reference please keep this manual in a safe place.

Thank you for specifying a product from the Francis Searchlights range. All Francis products are designed to give complete customer satisfaction and are manufactured to the highest engineering standards in order to ensure optimum performance and service life.

The Francis LED range combines features proven over many years service in the most hazardous conditions in both marine and land installations.

In order to prolong the life and performance of your product, we recommend that you only specify Francis Searchlights spare parts. This will also ensure that any warranties on your equipment will not be invalidated. Information on spares ordering and parts is provided in this manual.

Should you ever need to contact Francis Searchlights Ltd. regarding your equipment, please quote the Product Serial Number at all times.

2 - Safety Precautions

The following instructions must be adhered to, in order to ensure a safe working environment and the safety of the user.

Note: When unpacking or manoeuvring the searchlight into its fixing position, suitable lifting points must be used in order to prevent damage to the equipment or personal injury.

- The high luminance of the LED can cause severe damage to the eye if viewed directly. ALWAYS wear suitable protective goggles when viewing the LED.
- Searchlights get hot. Never touch the unit when lit and always allow 15 to 20 minutes for cooling down after turning the searchlight off.
- Never place anything on or cover the searchlight when in use.
- Ensure the LED has cooled sufficiently before removal.
- Due to the vast range of LED modules available it may appear possible that more powerful LED's can be used in the equipment than for which it was designed. Even when the unit will physically accept a higher wattage LED, this substitution is not recommended and is dangerous. This action will also void any warranties on the equipment.

3 - Technical Information

This product has been designed to operate in accordance with the product specification. The LED300RC Twin Head searchlight has the following features:

- All marine grade materials and fixings.
- Powder coated & stove enamel paint finish.
- 385° horizontal rotation.
- Vertical movement $\pm 45^\circ$.
- Variable speed 1-23°/sec (Pan), 1-8°/sec (Tilt).
- RS485 connectivity & auto home positioning.
- Dimmable LED joystick panel.
- Remote focus facility 4° spot to 10° flood.
- Internal heaters.
- Toughened super clear Optiwhite front glass.
- Precision made optical glass lenses.
- Searchlight Weight 70Kg
- Driver Box Weight 8Kg
- Sealing – IP66 Gearbox, IP56 Searchlight & PSU IP66.

The searchlight also performs to the following optical data:

- | | |
|---------------------------------------|---|
| ■ Supply voltage | 110/240v |
| ■ Luminous Flux | 71,074 |
| ■ Colour temperature | 6000K |
| ■ Range | 4309 metres at 2 Lux based on 4° divergence |
| ■ Divergence | Spot 4° to Flood 10° |
| ■ Economical | 20,000-hour LED life |
| ■ Operational temperature with heater | -50°C |

In order that the searchlight operates correctly it is imperative that competent personnel are responsible for the installation, operation and servicing of this equipment. Failure to adhere to this advice may cause premature failure or incorrect operation of the searchlight, which may damage the equipment or cause personal injury.

4 - Unpacking and Installation Instructions

The following instructions should be read and fully understood prior to installing the equipment to ensure that the correct procedures are followed, and all safety precautions are observed.

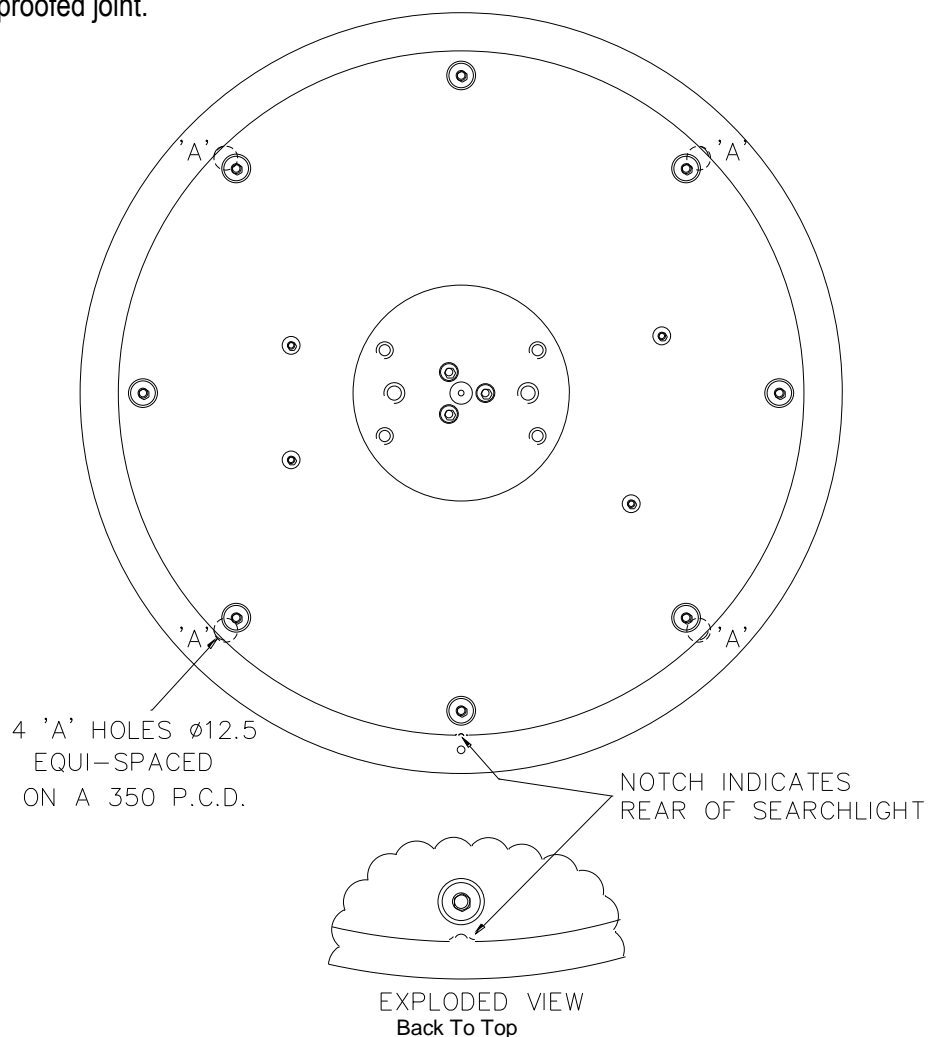
Note: If the equipment has been in storage for a considerable amount of time, it is advisable to conduct a routine maintenance check on all parts before installation.

Safety Precautions

This equipment should not be connected to an electrical supply before being installed. Installation procedures should be adhered to in order to ensure a safe working environment and reduce the risk of damage or personal injury.

Preparing the Mounting Position

Mark out and drill the fixing holes through the deck (refer to drawing C21501). If anti-vibration mounts are to be fitted, the fixing holes for the mounts should also be marked out and drilled. Prior to manoeuvring the searchlight into its' fixing position, the AV mounts should be fitted to the base. When in the desired position, bolt the searchlight firmly down. On an uneven surface it may be necessary to use a suitable sealant such as silicone, in order to ensure a weatherproofed joint.



5 - Electrical Installation

Note: ~

When the main power is first applied to the searchlight, the searchlight will carry out a self-test, it will Pan to the left limit and Tilt down to the limit, once this is complete, the searchlight will then move to the centre and horizontal, during this please do not try and operate the searchlight while this test is being carried out. Once the searchlight is back at centre the searchlight can then be operated normally, by pressing the 1/0 button on the control panel.

For safety purposes, only competent personnel should perform the electrical installation. All equipment should be installed to current Electrical Regulations and Standards.

In order to obtain the maximum light output from the searchlight, it is essential that the full operating voltage of the LED fitted be applied to the LED contacts.

Method of Electrical Connection

- 1) Disconnect the supply before working on the electrical system.
- 2) The searchlight must be connected to a fused electrical supply, using suitably sized cable.
- 3) If the searchlight is located a considerable distance from the supply, provision must be made in the cable size in order to overcome the voltage drop.
- 4) Whenever possible cable terminations should be made below deck and with approved terminal devices.
- 5) If a spare auxiliary fuse or circuit breaker is not available, one of the correct type/rating should be fitted and connected to a positive supply. It is advisable to locate a bus bar or main connection and avoid any direct connection to the supply:
- 6) For 110/220v AC products, the following colour coding system should be used for the customer supply cable:

Brown	- Live
Blue	- Negative
Green/Yellow	- Earth

Installation Guidelines

A typical installation and connection routine for the L300RC 468w LED Twin Head searchlight is as follows:

Referring to wiring diagram C28131 a supply is fed to the Driver/junction box, which then provides a common feed to the motor gearbox, searchlight and joystick panel.

The searchlight has been pre-wired with 3 meters of cable from the motor gearbox to the Driver/junction box provided. The searchlight heads are pre-wired along with the connecting cable to the motor gearbox.

Cables required to be connected by the customer: -

2 pair twisted 0.22mm 100ohm screened cable from the joystick panel to the Driver/junction box.

Supply cable to the Driver/junction box.

6 - Operating Instructions

This equipment is designed for use out of doors, in free air. Never place anything on or cover the searchlight when in use as this may present a hazard.

Switch On

The panel is activated using the 1/0 button. This will illuminate brightly when the panel is active.

Lamp Control

When the panel is active pressing the LIGHT, button will switch the lamp on or off. If the control panel is switched off with the 1/0 button the lamp will switch off.

Focus Control

The lamp focus can be adjusted using the FOCUS button. Lamp focus will adjust continuously whilst FOCUS is pressed.

Beam Direction

The beam direction can be adjusted using the joystick when the panel is active. Moving the joystick left or right will pan the beam clockwise or anticlockwise. Moving the joystick up or down will move the beam up or down. The speed of movement is proportional to the movement of the joystick. It is possible to move the beam in both directions at once by moving the joystick diagonally.

Home

The lamp can be returned to a pre-set home position. By default, this is dead ahead with the beam level although different positions can be programmed as described below.

Set New Home Position

To set a new home position move the lamp to the new desired home position. Switch the panel off then press the joystick down to its limit and press the lamp 1 button. The current position will now be the new home position.

Set Motion Limit (only available when Remote Focus is fitted)

The lamp travel can be limited in either axis and either direction. To set a new limit, switch the panel on and move the lamp to the desired limit position. Switch the panel off then press and hold the focus 1 button whilst moving the joystick full travel in the direction of the desired limit. Hold in this position for 4 seconds. For example, to set a limit to the tilt up motion; -

1. Switch panel on and drive the searchlight to the desired tilt up limit position.
2. Switch panel off.
3. Press and hold the FOCUS 1 button and hold joystick in the full up position for 4 seconds.
4. Tilt up motion will now be inhibited above the current position.

Clear Motion Limits

Motion limits as set above can be cleared by switching the panel off then pressing and holding the focus 1 button and lamp 1 buttons together for 10 seconds.

Adjusting Panel Illumination

The panel illumination intensity can be adjusted to suit ambient light levels. To adjust the intensity, switch the panel on then switch it off with the 1/0 button and keep the 1/0 button pressed. To increase intensity, move the joystick to the right. To decrease move to the left. Note that the 1/0 button must be kept depressed whilst the joystick is moved. All indicators will illuminate whilst adjustments are performed. Adjustment is complete when the 1/0 button is released.

Obtaining Fault Status

Fault codes can be accessed by switching the control panel on with the 1/0 button and keeping the 1/0 button pressed for 10 seconds. Fault codes are indicated by the 1/0 button flashing a number of times related to the fault. Fault codes are detailed below. If more than one fault is present the 1/0 button will indicate them in sequence.

1. Pan Limit. – Either of the pan limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e. the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
2. Tilt Limit. – Either of the tilt limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e. the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
3. Pan motor over current. – The pan motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
4. Tilt motor over current. – The tilt motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
5. Focus motor over current. – The focus motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
6. FBUS interface over current. – The speed control card supplies 24VDC to the remote-control panels. This fault indicates the 24VDC output is taking excessive current. The FBUS supply output will switch off. To restore this output, remove the supply from the speed control card for a period.

7. Anti-condensation heater output over current. – The 24VDC anti condensation heater output is taking excessive current. The heater output will switch off. To restore this output, remove the supply from the speed control card for a period.
8. Limit Switch Error. Some lamp types do not use all or some limit switches. If an invalid limit switch input is detected it is probable the speed control card is set to the wrong product or there is a wiring error.
9. Datum Error. The start-up datum system has not completed correctly.
10. Product type not set or corrupt. The product type has not been set, has been set incorrectly or is corrupt.
11. Supply voltage out of tolerance. The 24V supply is outside the range 18-30V.



FBUS SPEED CONTROL ASSEMBLY DETAILS

MAINS CONNECTORS

L Live.
N Neutral
E Earth

TILT CONNECTOR

MR Tilt Motor Red Wire (+)
MB Tilt Motor Black Wire (-)
ER Tilt Encoder Red Wire (5V). (Voyager Brown Wire)
EG Tilt Encoder Green Wire (Phase A Output) (Voyager Yellow Wire)
EW Tilt Encoder White Wire (Phase B Output)
OV Tilt Encoder Black Wire (Voyager Blue Wire)
Tilt Limit Switch Common Black Wire
UL Tilt up Limit Switch Orange Wire
DL Tilt down Limit Switch Blue Wire

PAN CONNECTOR

MR Pan Motor Red Wire (+)
MB Pan Motor Black Wire (-)
ER Pan Encoder Red Wire (5V)
EG Pan Encoder Green Wire (Phase A Output)
EW Pan Encoder White Wire (Phase B Output)
OV Pan Encoder Black & Pan Limit Switch Common
CL Pan Clockwise Limit Switch Orange Wire (As viewed looking down on lamp)
AL Pan Anticlockwise Limit Switch (As viewed looking down on lamp)

HEAD CONNECTOR

0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
H Heater Active High Output
F Focus Motor Active High Output
FP Focus position potentiometer

HEAD 2 CONNECTOR

0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
FP Focus position potentiometer
F Focus active high 5v output
L Lamp active high 5v output
24 24v supply out

FBUS CONNECTOR

0 0V out to Joystick Panels
T Line Terminate (Connect to + for terminate)
+ FBUS Data +
- FBUS Data -
24 24V Supply out to joystick panels

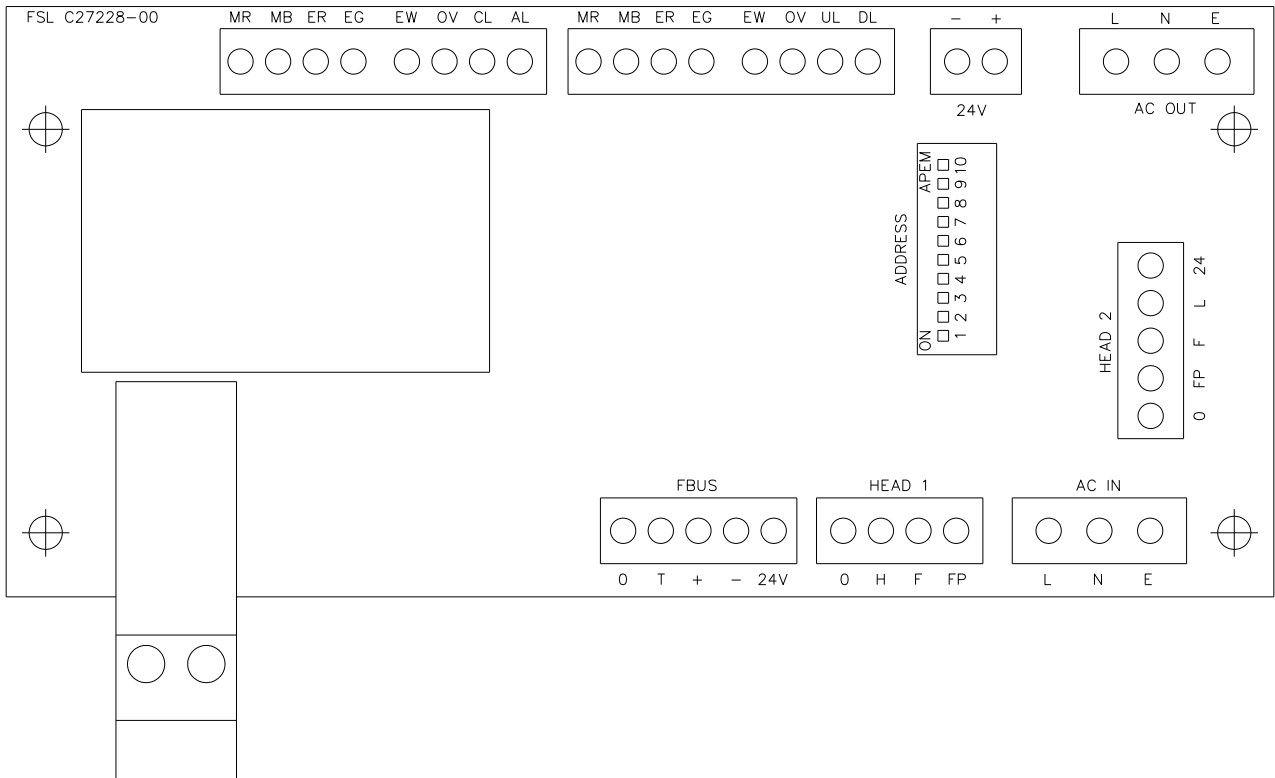
24 VOLT INPUT

- Negative
- + Positive

LAMP RELAY

- Relay input
- Relay output

FBUS Speed Control Board



FBUS EXTENSION CONTROL BOARD DETAILS

HEAD CONNECTOR

- 0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
- H Heater Active High Output
- F Focus Motor Active High Output
- FP Focus position potentiometer

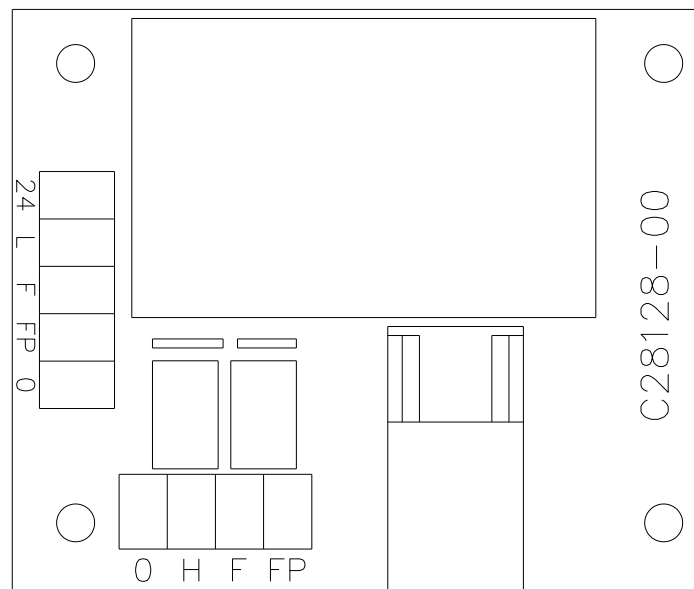
HEAD 2 CONNECTOR

- 0 0V Common for Heater & Focus (If Searchlight has an igniter terminal is not used)
- FP Focus position potentiometer
- F Focus active high 5v output
- L Lamp active high 5v output
- 24 24v supply out

LAMP RELAY

- Relay input
- Relay output

FBUS Extension Control Board



CONNECTIONS TO FBUS JOYSTICK CONTROL PANEL

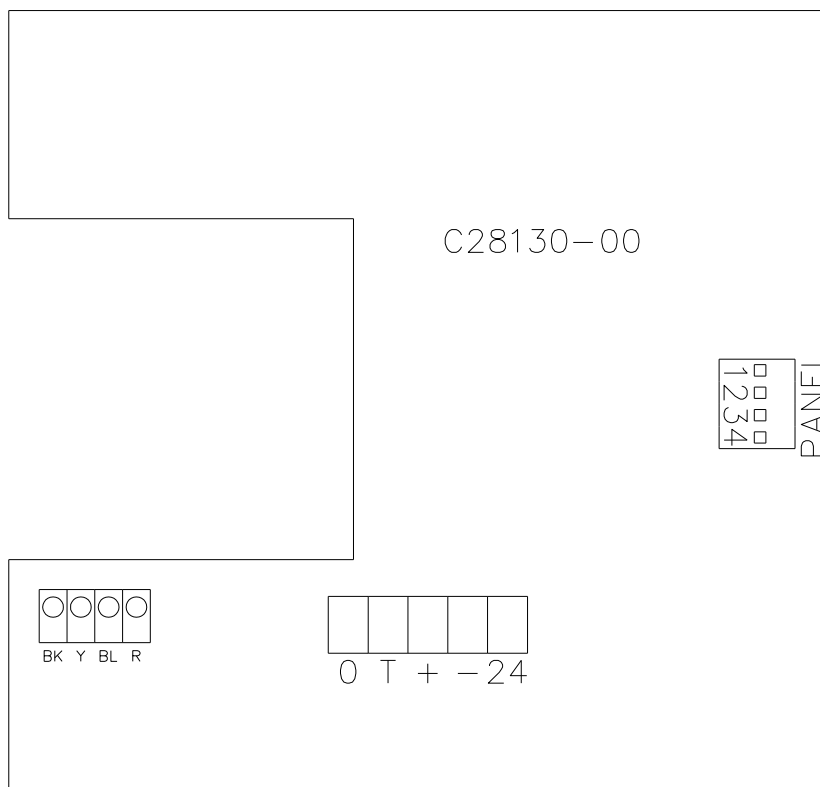
FBUS CONNECTOR

- 0 OV Supply Input
- T Line Terminate (Connect to + for terminate)
- + FBUS + RS485 Data In/Out
- FBUS - RS485 Data In/Out
- 24 +24V Supply Input

JOYSTICK CONNECTOR

- BK Joystick Black Wire
- Y Joystick Yellow Wire
- BL Joystick Blue Wire
- R Joystick Red Wire

FBUS JOYSTICK CONTROL BOARD



FBUS ADDRESS SWITCHES

OVERVIEW

FBUS uses two types of address switch. One type is rotary, and the value selected is the value shown on the dial. The other type is rows of switches whose operation is described below: -

The switches all operate in the same manner producing a binary value with the highest binary value to the left and the lowest value to the right. The values for each switch are listed below: -

SPEED CONTROL CARD LAMP ADDRESS

SWITCH NUMBER	VALUE
SWITCH 10	1
SWITCH 9	2
SWITCH 8	4
SWITCH 7	8
SWITCH 6	16

FBUS DATA PROTOCOL

OVERVIEW

The Francis bus (FBUS) is a custom communication protocol based on RS485 two wire bi-directional communication hardware. The system provides a simple bi-directional link between lamps and lamp control panels. The system allows given panels to communicate with different lamps and also allows a number of panels to communicate with the same lamp.

DETAILED DESCRIPTION

The FBUS system runs at 38.4K Baud. This low data rate facilitates longer cable runs and complements the fairly small amount of data transfer required whilst still providing a fast response. The data frame is 11 bits with 9 data bits, one start and one stop bit. A simple error detection system is employed which is described in detail later. Data is sent LSB first.

To prevent data collisions the system uses a polling technique. Lamp number 0 is the default bus master and controls timing of all communications by polling other units connected to the bus. If lamp 0 is not operating or powered down, lamp 1 automatically becomes the bus master as will lamp 2 if lamp 1 is not operating.

The system differentiates between address and data values by setting data bit 8 high for an address. Panel 2 address would therefore be sent as hex 102 or binary 100000010. The lamps and panels use different address ranges with panels being addresses 0-15 and lamp addresses starting at 16 and going up to 56. A lamp whose address was set to 0 on the address switches will actually be address 16 and would be transmitted as hex 110 or binary 100010000.

If lamp 0 is active this becomes the bus master and sequentially transmits the full address range. No other units will transmit until they receive their address. Each address is followed by a 1mS dead period where the master switches from transmit to receive and monitors the bus for activity. If activity is present the master will not transmit the next address until 1mS after bus activity ceases. After the full panel address range has been sent (addresses 0-15) the master starts to send lamp addresses.

These operate slightly differently in that, if more than three successive addresses do not illicit a response, the bus master will assume the last lamp has been polled and re starts the data cycle by reverting to panel address 0. When a remote panel receives its address, it will send data if it has any to send, if not, no data will be sent. Lamps operate differently in that they will always send data after they have seen their address on the bus. Panels can send data to any lamp therefore they transmit a modified lamp address value prior to the lamp command(s). The modified address is received by lamps and, if it matches their own address, the command(s) which follow will be received and processed.

A detailed description of panel and lamp data follows.

PANEL TRANSMITTED DATA

Panels only send data when there is data to be sent i.e., there has been activity at the panel which must be sent to a given lamp. If there is no data to be sent, a panel will not transmit. The amount of data a panel sends will depend upon the amount of activity at the panel and can be 2 to 10 bytes. The commands described below are sent after a panel receives its address which it uses as indication that it has a transmit time slot. Before any commands are sent the panel must define which lamp the data pertains to. This is achieved by preceding the command with a lamp address. Note that bit 7 is not set when a panel defines the lamp to which it is to transmit. Lamps recognise the address and receive data when the address matches their own. To send commands to lamp number 2 a panel would precede the lamp command(s) with the address value Hex 2, Binary 00000010. It is important to note that multiple commands must be sent in numerical order i.e., a command with value 01 must be sent before a command with 06 etc.

Panel transmit commands are listed below; -

DATA_PAN_JOYSTICK (Hex 01)

This is a two-byte command and must be immediately followed by another byte whose value determines the lamps direction and speed. The value is centred on 128 and has a range of 128 +/- 64. A value of 130 will make the lamp rotate slowly clockwise. Increasing the value will make the lamp move faster. A value of 126 will make the lamp rotate slowly anticlockwise. Decreasing the value will make the lamp move faster. Transmitting values 01 then C0 would make the lamp pan clockwise at full speed.

DATA_TILT_JOYSTICK (Hex 02)

This is a two-byte command and must be immediately followed by another byte whose value determines the lamps direction and speed. The value is centred on 128 and has a range of 128 +/- 64. A value of 130 will make the lamp point upwards slowly. Increasing the value will make the lamp move faster. A value of 126 will make the lamp move down slowly. Decreasing the value will make the lamp move faster. Sending values 02 then C0 would make the lamp tilt up at full speed.

DATA_LAMP_BUTTON (Hex 0A)

This is a single byte command. The same command is sent to switch the lamp on or off. This command must only be sent once for each press of the button. Sending again will switch the lamp again. Basically, if the lamp was off, sending this value will switch it on. If the lamp was on, sending this value will switch it off. This technique is employed to facilitate simultaneous lamp control from a number of different panels. Basically, what is sent is just information that the lamp on off button has been pressed. How the lamp reacts to this depends on the lamp's current status. Most of the other lamp button commands operate in a similar manner except the focus button. Confirmation that the command has been received can be obtained by reading the lamp status byte described below.

DATA_FOCUS_BUTTON (Hex 0B)

This is a single byte command. When the lamp receives this, it will run the focus motor as long as the command remains. A panel will send this command so long as the focus button is pressed.

DATA_HOME_BUTTON (Hex 0C)

This is a single byte command. A lamp receiving this will automatically move to the pre-set home position. The command does not need to be maintained while the lamp moves to home.

DATA_RECORD_BUTTON (Hex 0D)

This is a single byte command. The first time a lamp receives this command it will enter record mode and start monitoring all movement and lamp switching information. Recording will continue until the command is received again when it will stop recording. As with most of the button commands it is essential this command is just sent once. Confirmation that the command has been received can be obtained by reading the lamp status byte described below.

DATA_PLAY_BUTTON (Hex 0E)

This is a single byte command. The first time this is received a lamp will start playing back any movement / lamp switching activities which were recorded using the record function above. This will continue until the command is received again or the lamp receives a move command (DATA_PAN_JOYSTICK or DATA_TILT_JOYSTICK).

DATA_HOME_LP (Hex 0F)

This is a single byte command which activates when the home button is pressed and held for 5 seconds (Home Long Press). This is used to store a new home position. A lamp receiving this command will store the current position as the value to move to when the home button is pressed normally. Note that a lamp can only receive up to 10 bytes at a time. A panel's transmit sequence is the modified receiving lamp address followed by data commands then the CRC. The CRC is formed by the sum of all the commands + the lamp address value – note however that the address value used in the CRC is the unmodified value (Bit 7 clear).

DATA_PAN_POSITION (Hex 18)

This is a three-byte command. Following the DATA_PAN_POSITION command two data bytes specify the position to which the lamp must move. The bearing resolution is 0.1 degrees. The value is sent LSB first with the first byte representing the lower position command bits. The MSB (sent last) lower 4 bits represents the remaining value. The position value is centred on 2048 (Binary 1000 0000 0000) so a value of 2048 would make the lamp move to the dead ahead position. An increasing value represents a clockwise motion with a resolution of 0.1 degrees. A value of 2058 would therefore represent 1 degree clockwise (2058 = 2048 + 10 – but resolution is 0.1 degrees so a value 10 = 1 degree). Values below 2048 represent anticlockwise motion so a value of 1048 would represent an angle 100 degrees anticlockwise of centre.

DATA_TILT_POSITION (Hex 19)

This is a three-byte command. Following the DATA_TILT_POSITION command two data bytes specify the position to which the lamp must move. The bearing resolution is 0.1 degrees. The value is sent LSB first with the first byte representing the lower position command bits. The MSB (sent last) lower 4 bits represents the remaining value. The position value is centred on 2048 (Binary 1000 0000 0000) so a value of 2048 would make the lamp move to the dead ahead position. An increasing value represents tilting up with a resolution of 0.1 degrees. A value of 2058 would therefore represent 1 degree up from dead ahead ($2058 = 2048 + 10$ – but resolution is 0.1 degrees so a value $10 = 1$ degree). Values below 2048 represent tilting down so a value of 1748 would represent an angle 30 degrees down from centre.

LAMP TRANSMITTED DATA

A given lamp after it receives its normal address (Hex 110 to Hex 138) will always send the following data in this specific order. The lamp must transmit its first data byte (pan position) within 1mS of receiving its standard address and the gaps between successive bytes must be less than 1mS.

Lamp TX Byte 1 – Pan position LSB
Lamp TX Byte 2 – Pan position MSB
Lamp TX Byte 3 – Tilt position LSB
Lamp TX Byte 4 – Tilt position MSB
Lamp TX Byte 5 – Lamp status
Lamp TX Byte 6 – CRC

Each byte is described below.

Pan Position

This is a 12-bit value with lamp pointing straight ahead being a value of 2048 and the value increasing as the lamp rotates clockwise as viewed from above. The system has a resolution of 0.1 degrees so 90 degrees clockwise from centre would be a value of 2948 ($2048 + 900$).

Tilt position

This is a 12-bit value with lamp horizontal being a value of 2048 and the value increasing as the lamp beam points up. This has a resolution of 0.1 degrees.

Lamp Status

This is an 8-bit value with each bit representing a specific status aspect. The bit functions are listed below; -

Bit 0 - Lamp on
Bit 1 - Pan Limit reached
Bit 2 - Tilt Limit reached
Bit 3 - Lamp Recording
Bit 4 - Lamp Playing
Bit 5 - Lamp Overheated
Bit 6 - Lamp moving to home.
Bit 7 - Reserved

The bits are all true logic so if the lamp is switched on, bit 0 will be high.

CRC

The CRC is a simple data checking system. Basically, this is just the sum of the lamps address and bytes above. The value is radix to 8 bits. If the lamp address was 0 (bus address value 16) and the pan and tilt were both at centre and the lamp was switched on and all other status bits were 0 the values would be Hex 110, 80, 80, 01. This would give a CRC value of 11.

Each lamp connected to the bus will always send the data sequence above after it detects it's address on the bus. This is basically broadcast information which will be picked up by any panel whose lamp address value matches the currently transmitting lamp address. In this way a panel, which can access more than one lamp, will always update to reflect the status of the currently selected lamp more or less instantly.

EXTERNAL INTERFACE TO LAMPS

Interfacing to FBUS is simple. Any external interface must act as a slave and only send data when given an address slot. The address of an external interface can be any of the panel addresses providing these are not in use by other panels connected to the bus. To receive data from a lamp simply wait for the specific lamps address to be present on the bus then load the next six bytes which will comprise the lamps transmitted data as described above. A detailed description of transmitting and receiving is described below.

TRANSMITTING TO A LAMP

Basically, any sending device mimics a control panel. The full range of panel transmit commands, as described above, can be employed. Data can be sent to any lamp on the system. Two transmit examples are listed below.

EXAMPLE 1

Sending a lamp on/off command using panel 0 address and sending to lamp address 0. Note that the lamp will change switched state each time this command is sent therefore this should only be sent once.

1. Wait for panel address 0 (Hex 100) to be received from the bus.
2. Transmit lamp 0 address (Hex 110) within 1mS. Lamp address 0 is physical address 16 (Hex 10). When a panel sends to a lamp bit 8 is set (hex 100).
3. Send DATA_LAMP_BUTTON Command (Hex value 0A) within 1mS.
4. Send CRC value, in this case Hex 110 + Hex 0A = 11A after radix to 8 bits = 1A. This completes the transmission.

EXAMPLE 2

Sending a half speed pan clockwise command using panel 1 address and sending to lamp address 6. – Note that in this example the lamp will continue to pan as long as the command is repeated.

1. Wait for panel address 1 (Hex 101) to be transmitted by the master.
2. Transmit lamp 6 address (Hex 16) within 1mS. Lamp address 6 is physical address 22 (Hex 16).
3. Send DATA_PAN_JOYSTICK Command (Hex value 01) within 1mS.

4. Send pan value half speed = $128 + (64/2) = \text{Hex A0}$ within 1mS.
5. Send CRC value, in this case $\text{Hex } 116 + \text{Hex } 01 + \text{Hex } A0 = 1D7$ after radix to 8 bits = B7.
6. This completes the transmission.

RECEIVING FROM A LAMP

Lamps broadcast data sequentially. There is no need to actively request data to be sent, just wait for the lamps address with bit 7 set to be present on the bus and load the next six bytes. An example is given below; -

EXAMPLE

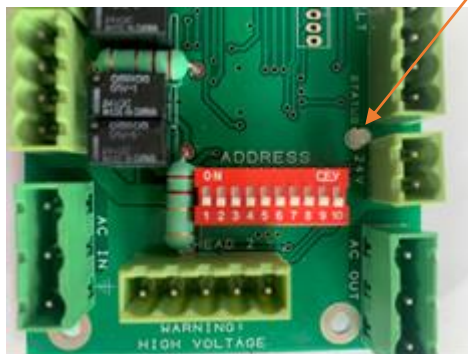
Obtain lamp number 2 pan position.

1. Listen to the data bus and wait for value Hex 112. (Lamp addresses start at hex 10 so lamp 2 is value 12. Addresses always have bit 8 set so total value is Hex 112).
2. Load the next six bytes from the bus.
3. If desired check the last of the six bytes which is the CRC.
4. Read the two bytes which will be a value centred on 2048 increasing for clockwise from centre and decreasing for anticlockwise. This is lamp number 2 current pan position.

FBUS Speed Control Assembly Status LED Operation

Overview

The FBUS motor control card has a status LED near the top of the card (labelled 'STATUS'). This has several functions as detailed below.



SOFTWARE VERSION

When power is applied to the speed control card the status LED will flash green. The number of flashes corresponds to the software version.

FBUS NORMAL OPERATION

When the system is operating from FBUS the status LED will illuminate static green. When a valid FBUS data signal is received the LED will switch off momentarily to indicate data reception. If data is continuous the LED will flash green slowly.

DMX NORMAL OPERATION

When the system is operating from DMX the status indicator will flash green slowly when DMX data is present. If no DMX data is present the LED will be static green.

OPERATION DURING FAULTS

During faults normal status LED operation is overridden. The status LED will flash red a number of times with the number of flashes corresponding to the specific fault. If there are multiple faults the LED will flash accordingly with a gap between each fault flash sequence. Fault details are provided below with the number of flashes indicated on the left.

1. Pan Limit. – Either of the pan limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
2. Tilt Limit. – Either of the tilt limit switches operated. Note that this may not actually be a fault. The LED will flash when a limit switch is operated under normal circumstances i.e., the lamp is at the limit of travel. This will also indicate when a variable limit is reached.
3. Pan motor over current. – The pan motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
4. Tilt motor over current. – The tilt motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
5. Focus motor over current. – The focus motor is taking excessive current. The motor will be disabled for a period when this occurs. Fault indication will remain until power is removed or the fault is corrected.
6. FBUS interface over current. – The speed control card supplies 24VDC to the remote-control panels. This fault indicates the 24VDC output is taking excessive current. The FBUS supply output will switch off. To restore this output, remove the supply from the speed control card for a period.
7. Anti-condensation heater output over current. – The 24VDC anti condensation heater output is taking excessive current. The heater output will switch off. To restore this output, remove the supply from the speed control card for a period.
8. Limit Switch Error. Some lamp types do not use all or some limit switches. If an invalid limit switch input is detected it is probable the speed control card is set to the wrong product or there is a wiring error.

9. Datum Error. The start-up datum system has not completed correctly.
10. Product type not set or corrupt. The product type has not been set, has been set incorrectly or is corrupt.
11. Supply voltage out of tolerance. The 24V supply is outside the range 18-30V.

FBUS CONTROL INSTALLATION AND OPERATION.

OVERVIEW

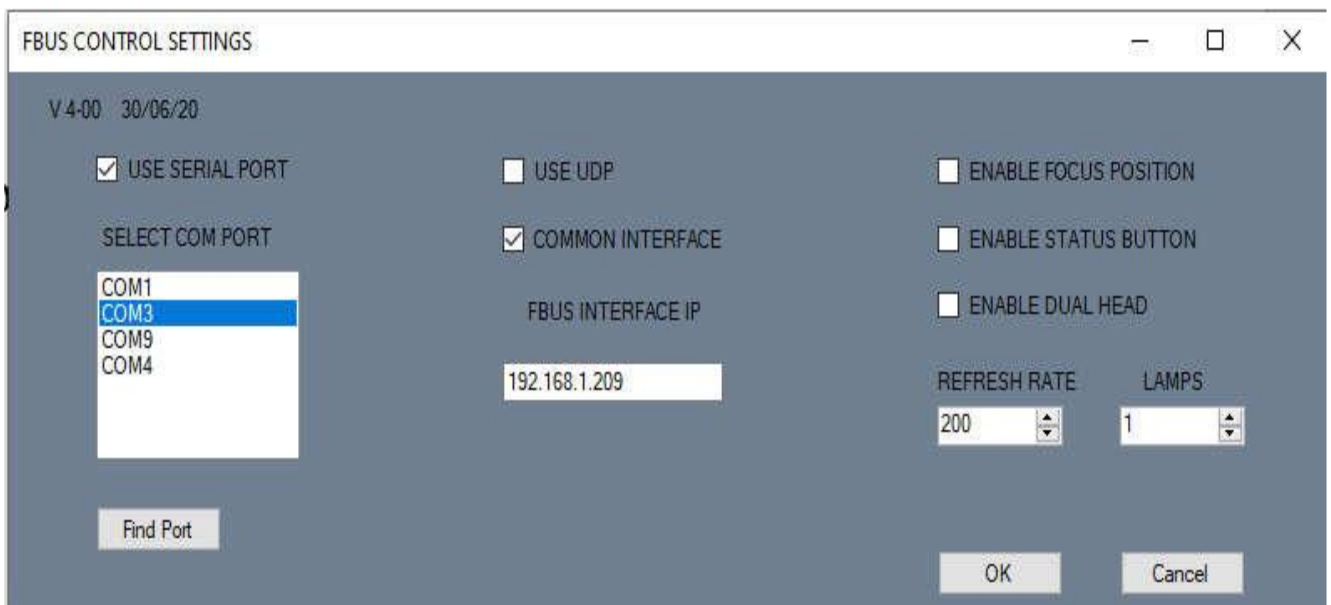
FBUS Control facilitates control of up to 12 searchlights from a PC. The system communicates to Francis Searchlights FBUS data system using one or more FBUS Interface units. Communication between the PC and FBUS interface can be RS485, RS422, USB (VCP) or UDP.

SOFTWARE INSTALL

Open the FBUS Control ZIP file and click 'Setup'. Windows should provide prompts to complete the installation.

CONFIGURATION

Start FBUS Control and press the SETTINGS button. The window below should display.



COMMUNICATION SETTINGS

Settings must be configured to suit the application. For systems where FBUS Control communicates with the FBUS Interface via a serial link (RS422, RS485 or USB), the USE SERIAL PORT tick box should be checked. The desired com port can now be selected. To find the correct com port, set the FBUS interface to the correct communication protocol and set the data rate to 9600K. Connect the data cable. Press the FIND PORT button. A message box should display the port number relating to the FBUS interface and the correct port will be set in the SELECT COM PORT text box.

For systems using UDP Communications (Ethernet / internet) the USE UDP checkbox should be set. When using UDP, FBUS control can operate in two ways.

For systems where all lamps are controlled from the same FBUS data system, the COMMON INTERFACE check box should be set. With this configuration the system will communicate to one FBUS interface. The second mode facilitates communication with lamps in different locations using a number of FBUS interfaces with independent IP Addresses. For this mode, the COMMON INTERFACE tick box should be cleared.

The SETTINGS window will now change as detailed below; -

FBUS CONTROL SETTINGS

V 4-00 30/06/20

USE SERIAL PORT USE UDP ENABLE FOCUS POSITION

SELECT COM PORT COMMON INTERFACE ENABLE STATUS BUTTON

COM1
COM3
COM9
COM4

LAMP BUTTON No FBUS INTERFACE IP FBUS LAMP No

1 192.168.1.209 0

REFRESH RATE LAMPS

200 1

Find Port OK Cancel

The new settings allow each lamp to communicate to a different FBUS Interface with an independent IP address. It is also possible for the system to control a number of lamps on one interface and more lamps on another interface. The IP address of the interface relating to each lamp should be entered in the FBUS INTERFACE IP box and the lamp No to be controlled on a given FBUS system to be entered into The FBUS LAMP No box. The LAMP BUTTON No indicates the lamp button corresponding to the settings displayed. For example, suppose a three-lamp system with two lamps connected to one FBUS interface (IP address 000.000.000.001) and a

third lamp connected to a different FBUS interface (IP address of 000.000.000.002).

To configure the system set LAMP BUTTON No to 1. Enter 000.000.000.001 for the IP address. Set FBUS LAMP No to 0. Change LAMP BUTTON No to 2 and set IP address to 000.000.000.001. Set FBUS LAMP No to 1. Now set LAMP BUTTON No to 3 and enter IP address 000.000.000.002. Set FBUS LAMP No to 0.

This system will control three searchlights the first two being connected to an FBUS interface at location A. The third lamp is controlled from a separate FBUS interface at location B.

OTHER SETTINGS

LAMPS

This should be set to the total number of lamps to be controlled. Once the settings window closes a number of lamp buttons will appear on the main window relating to the LAMPS Setting. Note that for single lamp systems LAMPS should be set to one.

For a single lamp there will not be any lamp buttons as there is only one selection possible.

REFRESH RATE

This controls the rate at which data packets are sent from FBUS Control. The value is in Milliseconds and must be set to suite the network conditions.

ENABLE FOCUS POSITION

Some lamp types provide a value relating to the lamps Focus. Setting this checkbox displays the Focus setting in the main window.

ENABLE STATUS BUTTON

For all new systems this should be set. Its inclusion is just for compatibility with legacy systems.

ENABLE DUAL HEAD

Some searchlights have dual heads with 2 separate lamp units. Setting this box display buttons for control of the second head.

Once all settings are complete close the settings window using the OK button. If settings are valid the software will restart with the new settings applied.

OPERATION

FBUS Control is very simple to use. The controls are detailed below; -

LAMP X Buttons (OPTION)

For systems which control just one lamp, the NUMBER OF LAMPS setting in the SETTINGS window should have been set to one. If this is the case, there will not be lamp buttons.

For systems with more than one lamp, the desired lamp should be selected with the appropriate LAMP X button. The button will change colour indicating lamp selection.

All subsequent commands will be directed to the selected lamp and all displayed information will pertain to the selected lamp.

LAMP ON / OFF Buttons

These switch the lamp on and off. The 'LAMP ON' button will illuminate red to indicate when the lamp is switched on. If the DUAL HEAD option in SETTINGS is set, there will be lamp on off button for each lamp head.

If the currently selected lamp is switched on or off from a different control station the lamp on the LAMP ON button will change to indicate the current lamp status.

FOCUS

When this button is selected with the mouse the lamp focus will operate adjusting the lamps beam width as long as the left mouse button is held down over the button. If the DUAL HEAD option in SETTINGS is set, there will be two focus buttons.

HOME

If a valid home position has been set, pressing the home button will cause the lamp to drive to the home position. The home button will turn red while the lamp is moving.

If another control station sets the lamp to home, the home button will turn red while the lamp is moving to home.

PLAY

The FBUS system can store and recall sequences of lamp motion and lamp on / off switching. Pressing the play button will start playing back a pre-recorded sequence. The play button will turn red when a sequence is playing. If another control station switches the lamp to play the button will turn red.

SET HOME

This button sets the current lamp position as the home position. The lamp will move to this position when the Home button is pressed.

RECORD

Pressing Record begins a record sequence. Lamp movements and lamp on off switching will be stored while the record system is active. Pressing Record again finishes the record sequence. Note that when Record is pressed a message box will appear asking the user to confirm the record command. This is included to prevent accidental over writing of previously recorded sequences. The record button will turn red while recording is active. If a different control station initiates recording the record button will turn red.

VIRTUAL JOYSTICK

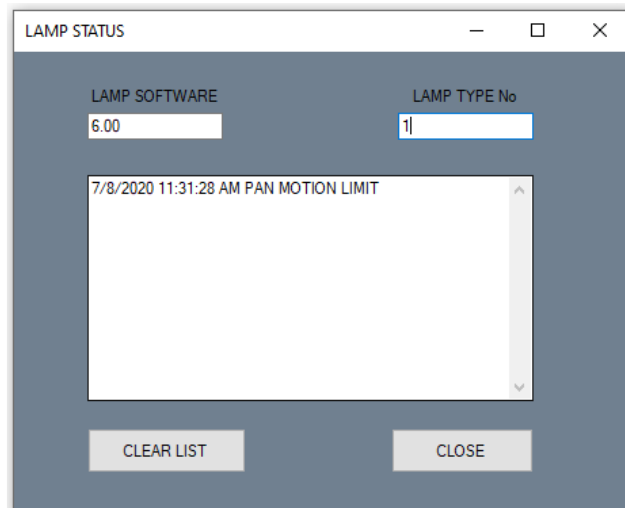
The virtual joystick is the dark grey circle near the bottom left of the FBUS Control window. The virtual joystick facilitates lamp pan and tilt movement. To move the lamp up (Tilt up) move the mouse over the yellow dot at the centre of the virtual joystick. Press and hold the left mouse button and move the yellow dot up from centre. The lamp will start to tilt up. The speed of tilt is proportional to the yellow spot distance from the centre of the joystick area. To make the lamp tilt down move the yellow dot down. To make the lamp pan left or right use the same procedure but move the yellow dot left or right. Moving the dot diagonally will cause both axes to operate together.

POSITION VALUES

The position window displays the currently selected lamps position. The values for pan and tilt are both +/- referenced from mid centre. The display values are in degrees with a resolution of 0.1 degrees. The selected lamp can be commanded to move to a specified position using the up / down buttons adjacent to the pan and tilt angle displays. When the angle is adjusted locally the GO button will highlight. Once the desired position is set press the GO button. The lamp will drive to the position entered.

STATUS

Pressing the Status button brings up the LAMP STATUS window below; -



The LAMP STATUS window lists any events or faults relating to the selected lamp.

This can be useful for fault diagnosis. The list can be cleared allowing all events after a given time to be reported. The LAMP STATUS window also displays the currently selected lamps software version and lamp type No

FBUS INTERFACE UNIT (if supplied)

OVERVIEW

Francis Searchlights FBUS data system facilitates control of up to 30 searchlights from multiple control stations. To provide the required control response whilst maintaining a low data rate for extended transmission distance, the FBUS data system involves precisely timed control signals.

The FBUS interface offers a simplified communication interface to the FBUS data system over a number of different physical layer communication standards and data rates. The system also facilitates long range communications over LAN / Internet.

When used with Francis searchlights FBUS Control software the FBUS interface can control networks of lamps over local communication systems or globally via the internet.

POWER / FBUS CONNECTION

The FBUS interface obtains a supply from the FBUS data system, no external power supply is required. The interface connects to the four wire FBUS system like any FBUS system component. The four-wire interface provides 24V supply and RS485 communications with FBUS.

EXTERNAL INTERFACE AND CONNECTIONS

The FBUS interface supports RS422 (4 wire), RS485 (2 wire), USB (VCP) and UDP.

Connections are detailed below; -

RS485

0 Common 0V

+ Data +

- Data -

RS422

0 Common 0V

Out + Data + out from interface

Out - Data - out from interface

In + Data + into interface

In - Data - into interface

USB

Type B Socket

Ethernet (UDP)

RJ45

OPERATOR INTERFACE

Four buttons control a simple menu system with a 2-line LCD display. A given menu item is selected with the SEL (select) button. If the menu item has an adjustable parameter this can be altered using the up and down arrow keys. The revised parameter is stored using the ENT (enter) button. A list of the menu items is provided below; -

MENU ITEMS

DEFAULT DISPLAY

The default display will be active from switch on until the select button is pressed. The default display has no adjustable parameters. The display indicates the FBUS status and currently selected lamp status.

SET PANEL ADDR

FBUS interface functions like a standard control panel on the FBUS system as such it must have a panel address. The panel address must not be set to the same value as any other panel on the system. Panel addresses start at 0 and go up to 15. Panel addresses should be sequential and start from zero. Once set pressing ENT stores the address.

SET LAMP ADDRESS

The interface unit has menu items (described below) which send commands directly to a given lamp. The default display described above displays data from a given lamp. The set lamp address item is used to define the 'given lamp' number. Note that this setting does not alter the interface operation with external data relating to communication with different lamps. A command to the interface will send data to the lamp number specified in the data packet.

SET COMMS TYPE

Selects the physical layer communication system for the external interface. Options are RS485, RS422, USB (VCP) and UDP.

SET DATA RATE

Selects the data rate for the external interface. Note that data rate adjustment is not allowed for UDP. When using the interface with FBUS Control software the data rate must be set to 9600 Baud.

DATA CHECKING

Used to enable or disable received data checking for the external interface. Switching data checking off can be useful during external communication system development.

This does not inhibit CRC transmission or FBUS data checking.

SWITCH LAMP

A function included principally to aid external interface development and verify

correct FBUS / lamp operation. Use the arrow keys to select lamp on or lamp off from line 2 of the display. Pressing ENT will send the on or off command to the currently selected lamp (see set lamp address).

SET PAN ANGLE

For system development and testing, this command sends a move to pan position command to the currently selected lamp. The pan angle is set using the arrow keys. Pressing ENT will move the lamp to the displayed angle.

SET TILT ANGLE

For system development and testing, this command sends a move to tilt position command to the currently selected lamp. The tilt angle is set using the arrow keys. Pressing ENT will move the lamp to the displayed angle.

FOCUS

For system development and testing, this function is not implemented on all searchlights. Focus displays the current focus position with a value of 0-100. A value of 50 should represent the most focused beam with the beam diverging above and below 50. Note that the value will ascend from 0-100 then reset back to 0. Pressing the arrow up button will operate the focus motor.

FAULTS+LIMITS

Displays any faults or limit switch activation relating to the selected lamp. Multiple faults will be displayed sequentially.

LAMP SOFTWARE

Displays the currently selected lamp software version.

LAMP TYPE No

Displays the lamp type number. FBUS Lamp control cards are generic and are programmed to the correct lamp type during lamp assembly. This setting facilitates verification of the lamp type setting.

EXT COMMS DATA

Included to aid external interface development. The display bottom line will show any valid received commands preceded by the lamp number to which the command is sent. The system also indicates data errors.

FBUS SUPPLY

This just indicates the FBUS supply voltage. FBUS operates at 24V. Values above 30 or below 18 indicate something is wrong.

NOTE – The remaining menu items can only be selected when communications is set to UDP.

REMOTE ADDRESS (UDP Only)

A diagnostic tool to display the IP address of the last remote system to communicate with the FBUS Interface.

The following menu items will select once the system has read the Ethernet interface parameters.

IP ADDR (UDP Only)

This displays the interface units IP address. To change the IP address press ENT. Note that the system must use static IP addressing.

GATEWAY ADDRESS (UDP Only)

This is a diagnostic tool to display IP address of the gateway if applicable.

EXTERNAL DATA INTERFACE – RECEIVED COMMANDS

External data must send command data packets with between four and seven bytes including the CRC.

The system uses standard 8-bit data transfer with 1 start bit and 1 stop bit. Data is sent least significant bit (LSB) first.

All command packets must start with a sync byte. The sync byte value is 0xFF. The next byte is the lamp address. The lamp address is a value between 0x90 and 0xA8. Lamp 0 address would therefore be sent as 0x90. The lamp address indicates to which lamp on the system the remaining data is to be directed. The next byte is the command. Some commands have subsequent data bytes. After the command (and data where applicable) a CRC is sent. All commands are detailed below; -

DATA_LAMP_BUTTON (0x0A)

Four-byte command (Sync, Lamp address, command, CRC). Switches the lamp state from on to off or off to on.

DATA_FOCUS_BUTTON (0x0B)

Four-byte command (Sync, Lamp address, command, CRC). operates the focus motor momentarily. To keep the focus motor running the command must be sent repeatedly. For systems where the data refresh rate is low see FOCUS_ON Command below.

DATA_MOVE_TO_HOME (0x0C)

Four-byte command (Sync, Lamp address, command, CRC). Lamp automatically moves to the home position. If a home position has not been defined the home position will be straight ahead with the lamp horizontal.

DATA_RECORD (0x0D)

Four-byte command (Sync, Lamp address, command, CRC). The lamp will start recording motion and lamp on / off data when this code is received.

DATA_PLAY (0x0E)

Four-byte command (Sync, Lamp address, command, CRC). The lamp will start playing back a previously recorded sequence when this code is received.

DATA_STORE_HOME (0x 0F)

Four-byte command (Sync, Lamp address, command, CRC). Stores the lamp current pan and tilt position values and will move to these values when the

DATA_MOVE_TO_HOME command is issued.

DATA_LAMP2_BUTTON (0x12)

Four-byte command (Sync, Lamp address, command, CRC). Switches the lamp second head state (if fitted) from on to off or off to on.

DATA_FOCUS2 BUTTON (0x13)

Four-byte command (Sync, Lamp address, command, CRC). operates the head 2 focus motor momentarily (if fitted). To keep the focus motor running the command must be sent repeatedly. For systems where the data refresh rate is low see FOCUS_HEAD2_ON Command below.

DATA_PAN_CLOCKWISE (0x14)

Five-byte command (Sync, Lamp address, command, speed, CRC) Pans the lamp clockwise at a speed proportional to the commanded value. The speed value is between 0 and 127. Value 0 stops pan motion and cancels the command. Increasing values make the lamp move progressively faster. Transmitting codes 0xFF 0x90 0x14 0x7F would move lamp 0 full speed clockwise. Note that this command will remain active until cancelled by sending the command with a 0-speed value.

DATA_PAN_ANTICLOCKWISE (0x15)

Five-byte command (Sync, Lamp address, command, speed, CRC) Pans the lamp anticlockwise at a speed proportional to the commanded value. The speed value is between 0 and 127. Value 0 stops pan motion and cancels the command. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x90 0x15 0x7F would move lamp 0 full speed anticlockwise. Note that this command will remain active until cancelled by sending the command with a 0-speed value.

DATA_TILT_DOWN (0x16)

Five-byte command (Sync, Lamp address, command, speed, CRC) Tilts the lamp down at a speed proportional to the commanded value. The speed value is between 0 and 127. Value 0 stops pan motion and cancels the command. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x92 0x16 0x7F would move lamp 2 down at full speed. Note that this command will remain active until cancelled by sending the command with a 0-speed value.

DATA_TILT_UP (0x17)

Five-byte command (Sync, Lamp address, command, speed, CRC) Tilts the lamp up at a speed proportional to the commanded value. The speed value is between 0 and 127. Value 0 stops pan motion and cancels the command. Increasing values make the lamp move progressively faster. Transmitting codes Hex 0xFF 0x92 0x17 0x7F would move lamp 2 up at full speed. Note that this command will remain active until cancelled by sending the command with a 0-speed value.

DATA_MOVE_TO_PAN_POSITION (0x18)

Six-byte command (Sync, Lamp address, command, Pan LSB, Pan MSB, CRC).

Commands the selected lamp to move to a specified pan position.

The position value is centred on a value of 2048. Values below 2048 represent negative angles, values above 2048 represent positive values. The resolution is 0.1 degrees.

A value of 2148 would represent + 10.0 degrees. ($2148 - 2048 = 100$).

A value of 1948 would represent -10.0 degrees ($1948 - 2048 = -100$).

Sending data 0xFF, 0x90, 0x00, 0x08, 0x17 would transmit a command to move to position 0.0 degrees.

DATA_MOVE_TO_TILT_POSITION (0x19)

Six-byte command (Sync, Lamp address, command, Tilt LSB, Tilt MSB, CRC). Commands the selected lamp to move to a specified tilt position.

The position value is centred on 2048. Values below 2048 represent negative angles, values above 2048 represent positive values. The resolution is 0.1 degrees.

A value of 2148 would represent + 10.0 degrees. ($2148 - 2048 = 100$).

A value of 1948 would represent -10.0 degrees ($1948 - 2048 = -100$).

Sending data 0xFF, 0x90, 0x00, 0x08, 0x17 would transmit a command to move to position 0.0 degrees.

DATA_LAMP_ON (0x1A)

Four-byte command (Sync, Lamp address, command, CRC). The lamp will switch on when this code is received.

DATA_LAMP_OFF (0x1B)

Four-byte command (Sync, Lamp address, command, CRC). The lamp will switch off when this code is received.

DATA_LAMP_HEAD2_ON (0x1C)

Four-byte command (Sync, Lamp address, command, CRC). If fitted the lamp head 2 will switch on when this code is received.

DATA_LAMP_HEAD2_OFF (0x1D)

Four-byte command (Sync, Lamp address, command, CRC). If fitted the lamp head2 will switch off when this code is received.

DATA_PAN_AND_TILT (0x32)

Five bytes (Sync, Lamp address, Pan command, Tilt command, CRC).

Drives the lamp pan and tilt motors at speeds / directions specified by the command values. The command values are centred on a value of 128 which represents a stop command. For the pan command, values above 128 will cause clockwise movement with the speed increasing as the value increases to a maximum of 0xFE. Values below 128 will cause anticlockwise movement

with the speed increasing as the value reduces, maximum speed will be 01. For the tilt command, values above 128 will cause the lamp to tilt up. The speed will increase as the value increases up to a maximum of 0xFE. Values below 128 will cause the lamp to tilt down with the speed increasing as the value reduces to a minimum of 01.

Note that these commands are maintained. Sending a command once will cause motion to start at the specified speed. This will continue until a command is sent with a zero (128) speed value.

DATA_POSITION (0x33)

Seven-bytes (Sync, Lamp address, Pan low, Pan high, Tilt low, Tilt high, CRC). This commands the selected lamp to move to a given position with both pan and tilt positions specified. The pan and tilt position value format are the same as for the DATA_MOVE_TO_PAN_POSITION command.

DATA_REQUEST_LAMP_STATUS (0x34)

Four-byte command (Sync, Lamp address, command, CRC). When the interface receives this command there is a 10mS delay then the interface will switch to transmit and send 13 bytes as detailed below.

1. Sync (FF)
2. Lamp Address with bit 7 set - range 0x90-0xA8
3. Pan Position LSB (Same format as pan position command above)
4. Pan Position MSB
5. Tilt Position LSB (Same format as tilt position command above)
6. Tilt Position MSB
7. Lamp Status

- Bit 0 - Lamp on
- Bit 1 - Pan Limit
- Bit 2 - Tilt Limit
- Bit 3 - Lamp Recording
- Bit 4 - Lamp Playing
- Bit 5 - Lamp head 2 on
- Bit 6 - Lamp moving to home.

8. Focus position - Value between 0 and 100 - Minimum beam width at value 50.

9. Fault Status 1

- Bit 0 - Pan motor current high.
- Bit 1 - Tilt motor current high.
- Bit 2 - Focus motor current high.
- Bit 3 - FBUS +24V out current high.
- Bit 4 - Heater current high.

10. Fault Status 2

- Bit 0 - Limit switch error.
- Bit 1 - Datum error.
- Bit 2 - Lamp type invalid.

Bit 3 - Supply voltage out of tolerance.

11. Lamp software version.
12. Lamp type No.
13. CRC

DATA_FOCUS_ON (0x35)

Four-byte command (Sync, Lamp address, command, CRC). Sets the focus motor running. Focus will continue to operate until a DATA_FOCUS_OFF command is received. This command is included to allow systems which have a low refresh rate to control the focus motor.

DATA_FOCUS_OFF (0x36)

Four-byte command (Sync, Lamp address, command, CRC). Stops the focus motor.

Used to cancel the DATA_FOCUS_ON command. This command is included to allow systems which have a low refresh rate to control the focus motor.

DATA_FOCUS_HEAD2_ON (0x37)

Four-byte command (Sync, Lamp address, command, CRC). Sets the head 2 focus motor running (when fitted). Focus will continue to operate until a DATA_FOCUS_HEAD2_OFF command is received. This command is included to allow systems which have a low refresh rate to control the focus motor.

DATA_FOCUS_HEAD2_OFF (0x38)

Four-byte command (Sync, Lamp address, command, CRC). Stops the head2 focus motor (when fitted). Used to cancel the DATA_FOCUS_HEAD2_ON command.

This command is included to allow systems which have a low refresh rate to control the focus motor.

ERROR CONTROL CRC

Error control is implemented with a CRC following each data packet. The CRC is radix to 7 bits giving a value between 0 and 127. The CRC is simply the addition of all packets data values including the address and start byte (0xFF). For example, a command to run lamp 0 focus motor would be 0xFF, 0x90, 0x0B. The addition of these values give 0x19A. The CRC would therefore be this value radix to 7 bits to give a value of 0x1A. This value is sent as the last byte of the packet.

DATA TIMING

Data packets can be sent up to 10 times per second. Each packet starts with value 0xFF. The remaining bytes should follow immediately. The whole packet must be received within 30mS. A packet lasting longer than 30mS will be rejected.

There is no minimum packet send rate.

When the FBUS interface receives the DATA_REQUEST_LAMP_STATUS command there is a 2-30mS delay after which the FBUS interface switches to

transmit and outputs 13 data bytes in direct succession. After the last byte has been sent the interface will switch back to receive.

7- Fault Finding

All fault finding must be conducted by a competent person or qualified Electrical Engineer.

Failure of LED to light.

In the event of the LED failing to light the following steps should be taken:

- 1) Check that the supply is connected to the input of the LED driver and check all connections as per the wiring diagram. On operation if the LED does not light, switch off mains supply and check all fuses.

NOTE: If a fault occurs on the pan and tilt gearbox, the unit should be returned to Francis Searchlights Limited for fault evaluation and repair.

8 - Maintenance and Servicing

In order to prolong the service life and performance of your searchlight, the following maintenance guidelines are recommended:

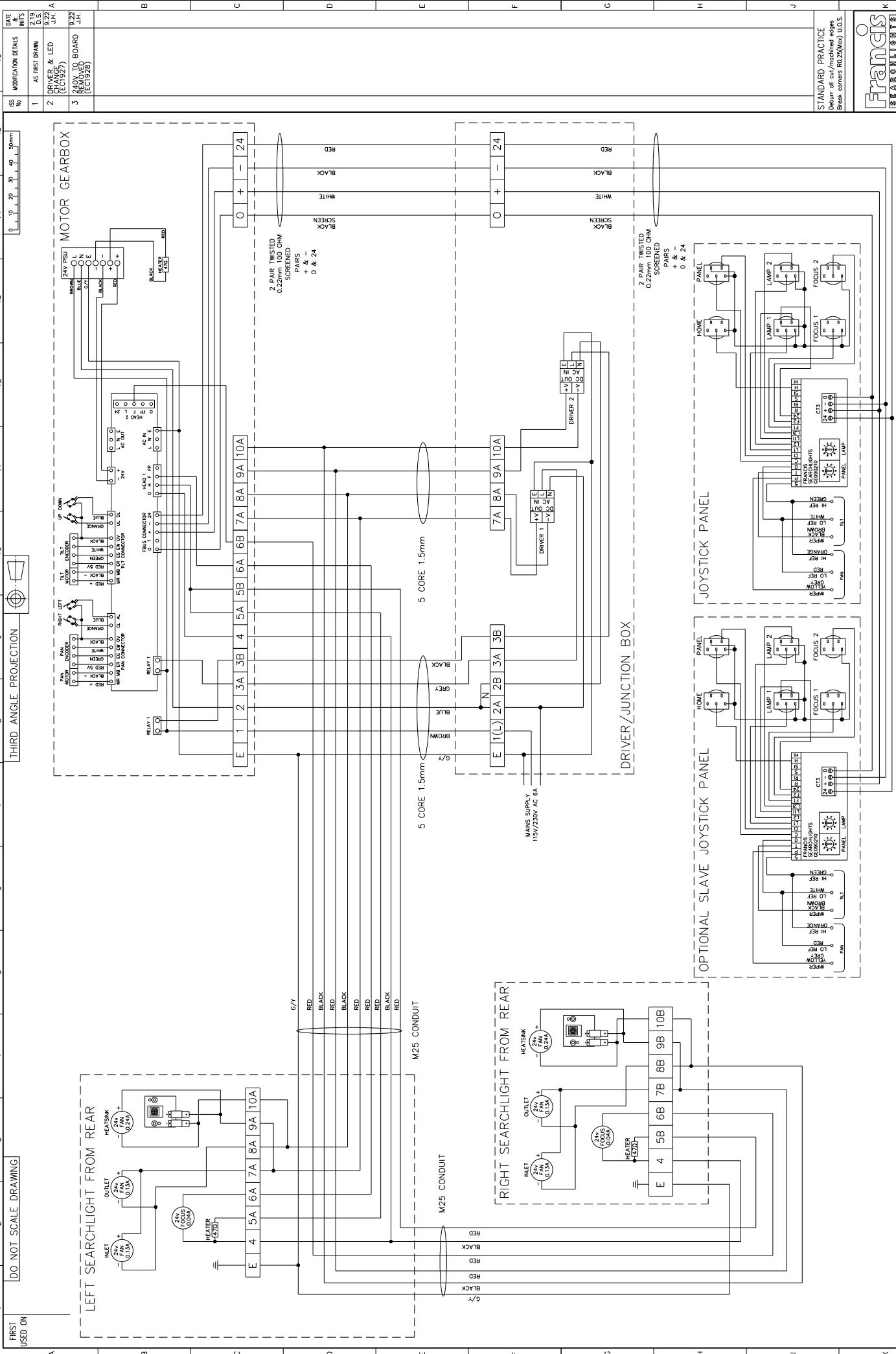
- Maintenance checks should be conducted before every voyage or at least every three months.
- Before checking, disconnect the equipment from the supply.
- Visually inspect the condition of the equipment.
- Any major or minor structural damage should be rectified immediately in order to reduce sympathetic wear.
- After inspection it may be necessary to clean the inside of the searchlight. The following procedure should be adhered to:
 - Remove the front bezel.
 - Clean the front glass inside and out using a proprietary glass cleaner.
 - Clean the lenses if required.
- It is advisable to check all seals and gaskets for signs of degradation. Renew if necessary.
- The searchlight is fitted with a breather unit. This ensures a steady airflow in order to prevent any vacuum forming within the barrel.
- Upon completing all maintenance requirements, the searchlight should be tested for full working order (approximately 20 minutes).

If in any doubt as to the correct servicing procedures to adopt, please contact your distributor/agent or the manufacturer who will be able to advise the best course of action for your product.

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9 - Wiring Diagram & General Assembly

Drawing Number	Description
A7177	L300RC 468w LED Twin Head General Assembly
C28131	Wiring diagram 115/240v
C28070	Joystick Panel Assembly
C28423	Optional Control Panel Enclosure Assembly
C28124	Driver Box Assembly 115/240v

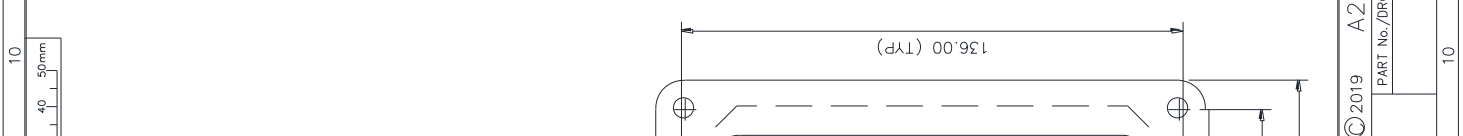


REV	NO	MODIFICATION DETAILS	DATE	INITIALS
1	1	AS FIRST DRAWN	2.19.05	J.H.T.
2	2	DRIVER & LED REWORKED (E-1957)	9.22.05	J.H.T.
3	3	240V TO BOARD (E-1925)	9.22.05	J.H.T.

STANDARD PRACTICE
 Drawn at cut/machine edge
 Break corners (0.25mm) U.O.S.

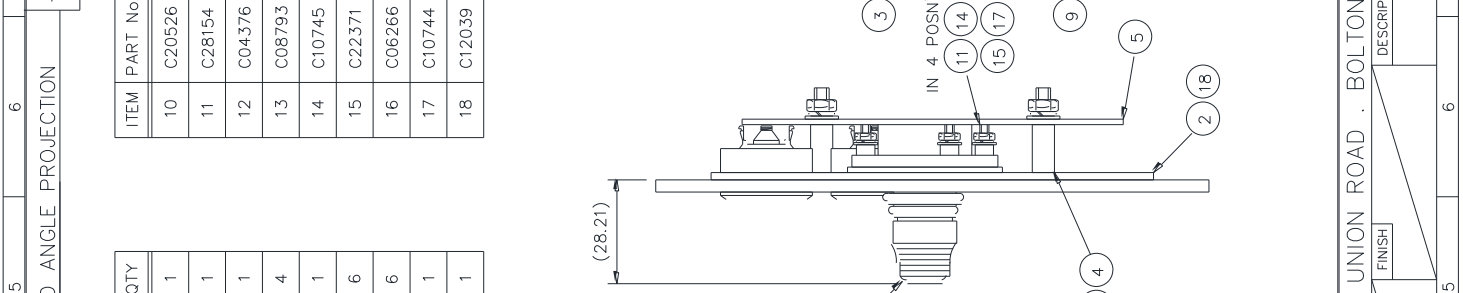


DRAWN	D.S.	DATE	28.2.19	TOLERANCES	FINISH	DESCRIPTION	16
CHECKED	SCALE			Conform to ISO 8062 C18		WIRING DIAGRAM (L300RC 468W LED TWIN HEAD)	15
ALL DIMENSIONS IN MILLIMETRES				As per drawing & poss. ±			14
							13
							12
							11
							10
							9
							8
							7
							6
							5
							4
							3
							2

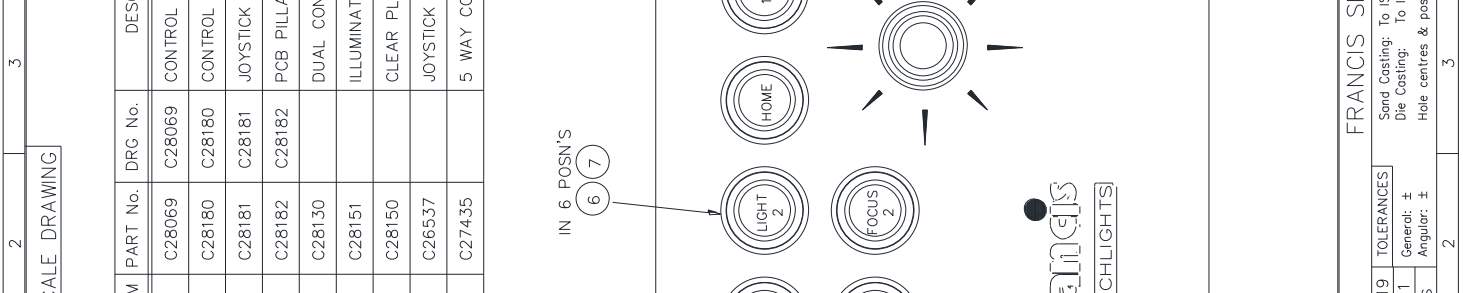


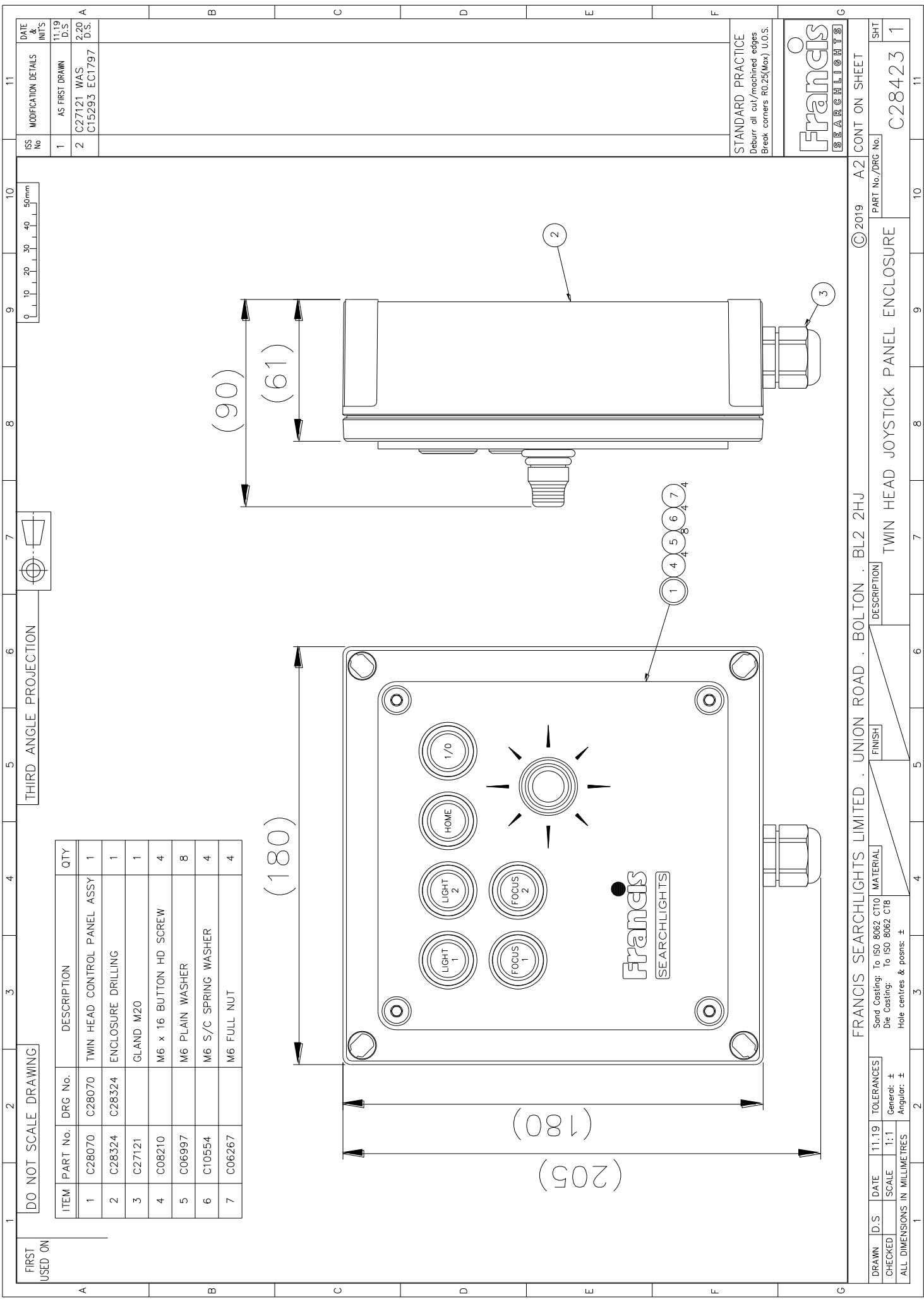
ITEM	PART No.	DRG No.	DESCRIPTION	QTY
10	C20526		M4 x 25 CSK HD SCREW	4
11	C28154		M2.5 x 16 CSK HD SCREW	4
12	C04376		M4 PLAIN WASHER	4
13	C08793		M4 S/C SPRING WASHER	4
14	C10745		M2.5 PLAIN WASHER	4
15	C22371		M2.5 S/C SPRING WASHER	4
16	C06266		M4 FULL NUT	4
17	C10744		M2.5 FULL NUT	4
18	C12039		CLEAR RTV	A/R

ITEM	PART No.	DRG No.	DESCRIPTION	QTY
1	C28069		CONTROL PANEL	1
2	C28180		CONTROL PANEL BACKING PLATE	1
3	C28181		JOYSTICK BACK PLATE	1
4	C28182		PCB PILLAR	4
5	C28130		DUAL CONTROL JOYSTICK PANEL BOARD	1
6	C28151		ILLUMINATED PUSHBUTTON	6
7	C28150		CLEAR PLASTIC LENS	6
8	C26537		JOYSTICK	1
9	C27435		5 WAY CONNECTOR	1



ITEM	PART No.	DRG No.	DESCRIPTION	QTY
1	C28069		CONTROL PANEL	1
2	C28180		CONTROL PANEL BACKING PLATE	1
3	C28181		JOYSTICK BACK PLATE	1
4	C28182		PCB PILLAR	4
5	C28130		DUAL CONTROL JOYSTICK PANEL BOARD	1
6	C28151		ILLUMINATED PUSHBUTTON	6
7	C28150		CLEAR PLASTIC LENS	6
8	C26537		JOYSTICK	1
9	C27435		5 WAY CONNECTOR	1





ISS No	MODIFICATION DETAILS	DATE & INIT'S
1	AS FIRST DRAWN	11.19 D.S
2	C27121 WAS C15293 EC1797	2.20 D.S. A

ITEM	PART No.	DRG No.	DESCRIPTION	QTY
1	C28070	C28070	TWIN HEAD CONTROL PANEL ASSY	1
2	C28324	C28324	ENCLOSURE DRILLING	1
3	C27121		GLAND M20	1
4	C08210		M6 x 16 BUTTON HD SCREW	4
5	C06997		M6 PLAIN WASHER	8
6	C10554		M6 S/C SPRING WASHER	4
7	C06267		M6 FULL NUT	4

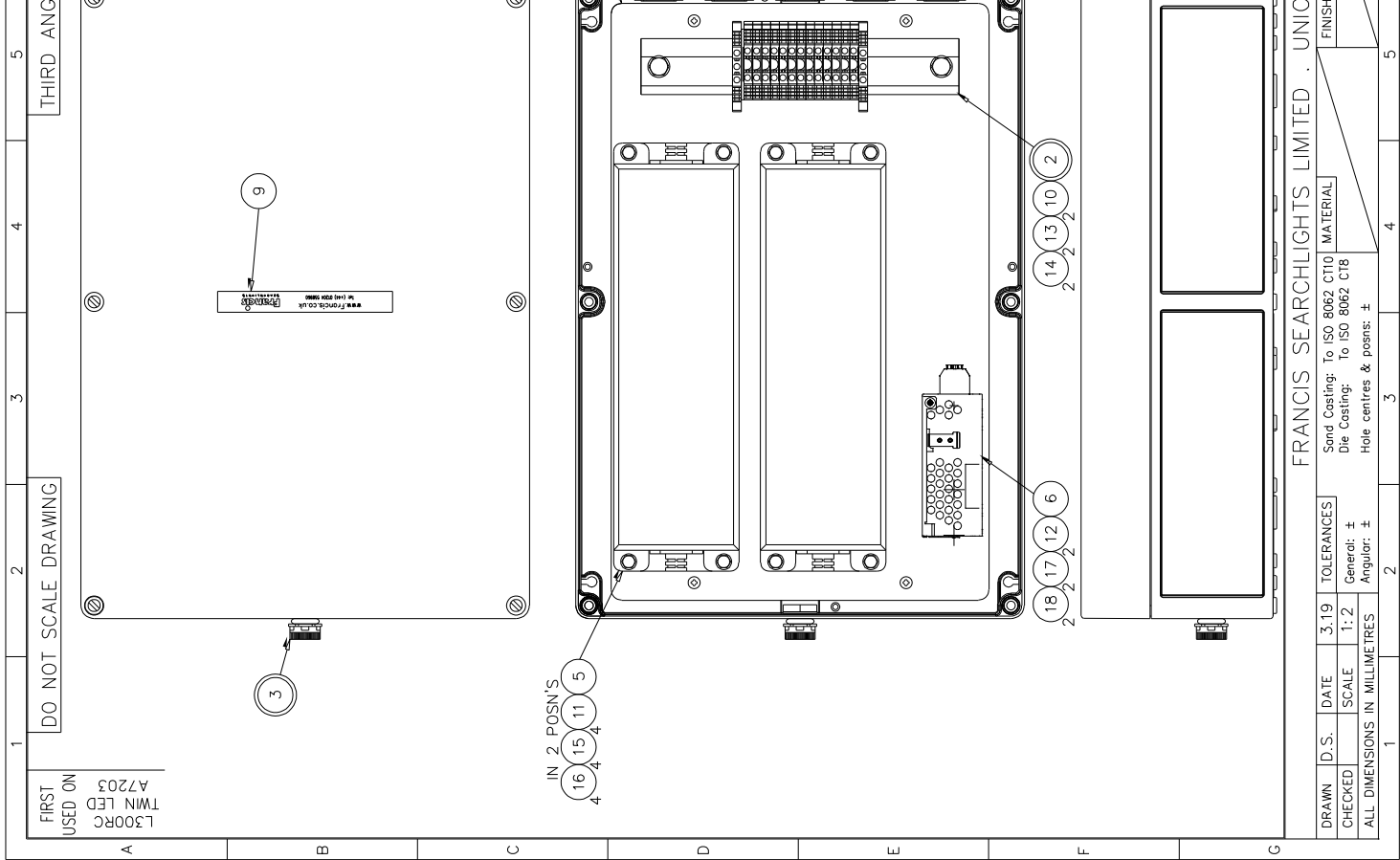
DO NOT SCALE DRAWING		THIRD ANGLE PROJECTION		FRANCIS SEARCHLIGHTS LIMITED . UNION ROAD . BOLTON . BL2 2HJ		CONT ON SHEET	
STANDARD PRACTICE Debur all cut/machined edges Break corners R0.25(Max) U.O.S.		PART No./DRG No. C28423		SHT 1		11	
DRAWN D.S		DATE 11.19		TOLERANCES		Send Casting: To ISO 8062 CT10	
CHECKED		SCALE 1:1		General: ±		Die Casting: To ISO 8062 CT8	
ALL DIMENSIONS IN MILLIMETRES		Angular: ±		Hole centres & posns: ±		FINISH	
				DESCRIPTION		TWIN HEAD JOYSTICK PANEL ENCLOSURE	

ISS No	MODIFICATION DETAILS	DATE & INITS
1	AS FIRST DRAWN	3.19 D.S.
2	NEW DRIVER & CHASSIS PLATE	8.19 LW
3	C27121 WAS	2.20 D.S.
4	NEW DRIVER, BOX WAS C28123, NOW C28520, C29655, C29033, ADD'D. (EC1927)	8.22 J.H.

ITEM	PART No.	DRG No.	DESCRIPTION	QTY
1	C29655	C29655	CHASSIS PLATE SUB ASSY	1
2	C28121	C28121	TERMINAL RAIL ASSY	1
3	C22268		BREATHER UNIT ASSY	1
4	C28520	C28520	DRIVER JUNCTION BOX DRILLING	1
5	C29601		LED DRIVER	2
6	C29033		24V PSU	1
7	C12415		M20 CABLE GLAND	3
8	C27121		M20 CABLE GLAND	2
9	C04900		FRANCIS EXTERIOR LABEL	1
10	C08120		M6 x 10 HEX HD SCREW	2
11	C26955		M4 x 10 HEX HD SCREW	8
12	C14502		M3 x 6 BTN HD SCREW	2
13	C06997		M6 PLAIN WASHER	2
14	C10554		M6 S/C SPRING WASHER	2
15	C04376		M4 PLAIN WASHER	8
16	C08793		M4 S/C SPRING WASHER	8
17	C08028		M3 PLAIN WASHER	2
18	C10747		M3 S/C SPRING WASHER	2

STANDARD PRACTICE
 Debur all cut/machined edges
 Break corners R0.25(Max) U.O.S.

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 FRANCIS SEARCHLIGHTS
 PART No./DRG No. C28124 1
 SHEET 1



FRANCIS SEARCHLIGHTS LIMITED . UNION ROAD . BOLTON . BL2 2HU	DESCRIPTION	FINISH	MATERIAL
	DRIVER BOX ASSY		Sand Coating: To ISO 8062 CT10 Die Coating: To ISO 8062 CT8
			Hole centres & posns: ±
			Angular: ±

DRAWN	D.S.	DATE	3.19	TOLERANCES
CHECKED	SCALE	1:2	General: ±	Angular: ±
ALL DIMENSIONS IN MILLIMETRES				

10 - Spare Parts List

The following spare parts can be ordered directly from the manufacturer:

Part Number	Description
Searchlight Spares	
C29668-01	LED Replacement Kit
C27224-00	Front glass
C20567-00	Front glass gasket
C22268-01	Breather Assembly
C20281-00	Bellows
C27288-01	Heater
C27820-00	Fan (Top & Bottom Vents)
C27820-00	Fan (Heatsink)
C16410-01	Focus Motor
C27143-00	Lens Ø200mm
C27144-00	Lens Ø180mm
C27145-00	Lens Ø114mm
C27146-00	Lens Ø77mm
C27147-00	Lens Ø74mm
Motor Gearbox Spares	
C27288-01	Heater
C27308-01	Pan Motor Sub Assembly
C27157-00	Tilt Motor
C22380-00	Micro switch no lever
C22382-00	Micro switch with lever
C29162-00	24v Power Supply Unit
C27187-01	Speed Controller PCB
C28128-00	Dual Head Extension PCB
C22381-00	Pedestal Top Sealing Gasket
C26441-00	Pedestal Cover Gasket
Driver Box	
C29601-01	LED Driver HV (2 Used)
C29033-01	24V PSU
C22268-01	Breather Assembly
Joystick Panel	
C26537-00	Joystick
C28130-00	Dual Control Joystick PCB
C28151-00	Illuminated Push Button
C28150-00	Clear Plastic Lens
C28149-00	Marking Plate
C27435-00	5-Way Connector

In order to prolong the life and performance of your product, we recommend that you only specify Francis Searchlights spare parts. This will ensure that any warranties on your equipment will not be invalidated.

When ordering spare parts please contact the Sales Department at Francis Searchlights Limited. Please quote searchlight model and serial number at all times. This will enable a fast response to your spares' requirements.

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